

**RECTILINEAR AND ROTATIVE
DISPLACEMENT TRANSDUCERS
ENCODERS.**



GEFRAN

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RECTILINEAR AND ROTATIVE DISPLACEMENT TRANSDUCERS / ENCODERS

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Main features

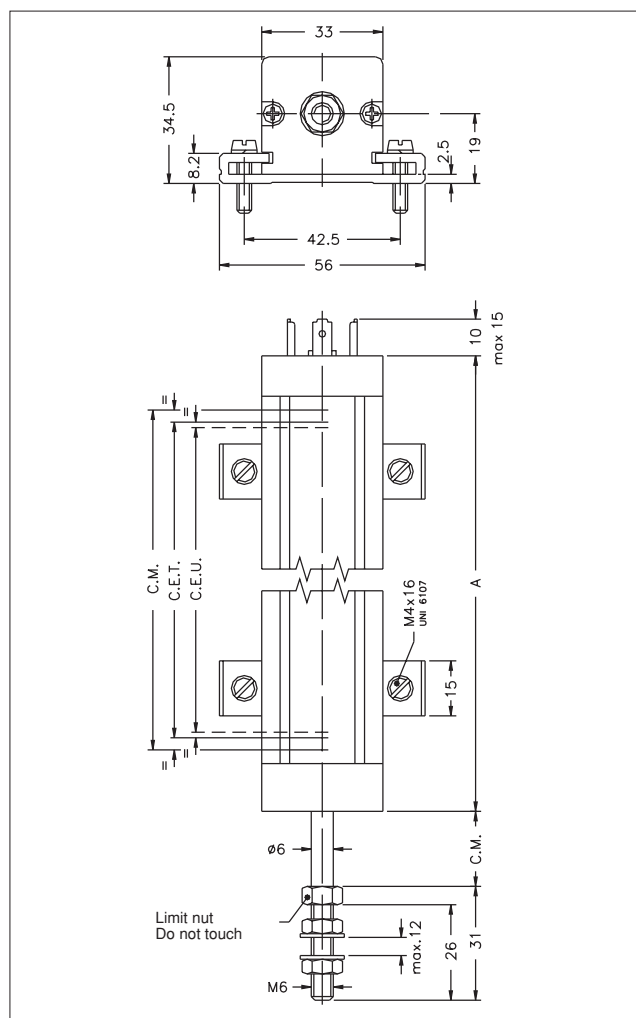
- 50 to 900 mm stroke.
- Mechanical linkage using M6 thread
- Independent linearity $\pm 0,05\%$
- Repetibility 0,01 mm.
- Infinite resolution
- No variation of electrical signal outside theoretical electrical stroke
- Displacement speed up to 5 m/s (optional 10m/s)
- Working temperature: $-30...+100^{\circ}\text{C}$
- Electrical connections:
 - LT H 3 pole connector
 - LT M 4 pole connector to standard DIN43650 ISO4400
 - LT B 5 pole connector DIN43322
 - LT F 3 pole screened cable (1m length).
- Life duration: $> 25 \times 10^6$ meters or $> 100 \times 10^6$ operations whichever is the smaller (within C.E.U.)
- Grade of protection IP60 (optional IP65)

TECHNICAL DATA

Useful electrical stroke (C.E.U.)	50/100/130/150/175/200/225/275/300/375/400/450/500/600/750/900
Independent linearity (within C.E.U.)	$\pm 0,05\%$
Displacement speed	Standard ≤ 5 m/s (optional ≤ 10 m/s)
Displacement force	$\leq 2\text{N}$ Version IP60 $\leq 10\text{N}$ Version IP65
Vibrations	5...2000Hz, $A_{\text{max}} = 0,75$ mm $a_{\text{max}} = 20$ g
Shock	50 g, 11ms.
Operative acceleration	200 m/s ² max (20g)
Tolerance on resistance	$\pm 20\%$
Recommended cursor current	$< 0,1 \mu\text{A}$
Maximum cursor current	10mA
Maximum applicable voltage	60V
Electrical isolation	$> 100\text{M}\Omega$ at 500V~, 1bar, 2s
Dielectric strength	$< 100 \mu\text{A}$ at 500V~, 50Hz, 2s, 1bar
Dissipation at 40°C (0W at 120°C)	3W
Temp. Coeff. of the resistance	$-200 \pm 200\text{ppm}/^{\circ}\text{C}$
Actual Temperature Coefficient of the output voltage	$< 1,5\text{ppm}/^{\circ}\text{C}$
Working temperature	$-30...+100^{\circ}\text{C}$
Storage temperature	$-50...+120^{\circ}\text{C}$
Case material	Anodised aluminium Nylon 66 GF 40
Control rod material	Stainless steel AISI 303
Fixing	Brackets with variable longitudinal axis

Important: all the data reported in the catalogue linearity, lifetime, temperature coefficient are valid for a sensor utilization as a ratiometric device with a max current across the cursor $I_c \leq 0.1 \mu\text{A}$.

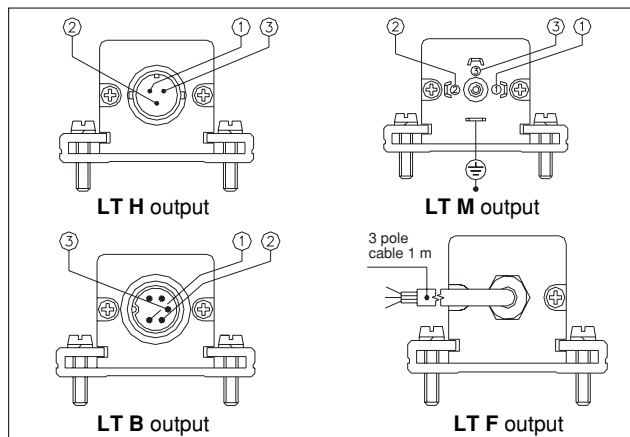
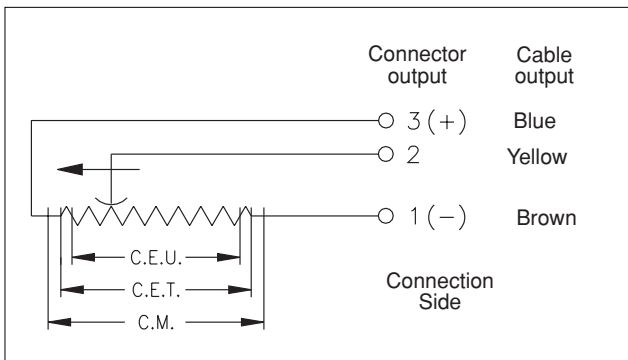
MECHANICAL DIMENSIONS



MECHANICAL / ELECTRICAL DATA

MODEL		50	100	130	150	175	200	225	275	300	375	400	450	500	600	750	900
Useful electrical stroke (C.E.U.) +3/-0	mm	50	100	130	150	175	200	225	275	300	375	400	450	500	600	750	900
Theoretical electrical stroke (C.E.T.) ±1	mm	C.E.U. + 3					C.E.U. + 4					380	406	457	508	609	914
Resistance (C.E.T.)	kΩ	5					5					5	5	5	5	10	10
Mechanical stroke (C.M.)	mm	C.E.U. + 9					C.E.U. + 10					386	412	463	518	772	924
Case length (A)	mm	C.E.U. + 62					C.E.U. + 63					439	465	516	571	825	977

ELECTRICAL CONNECTIONS



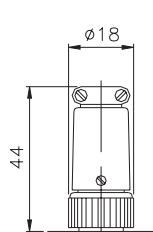
ACCESSORIES

STANDARD ACCESSORIES

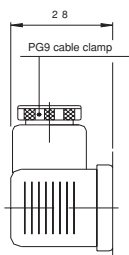
Fixing kit for LT: 2 brackets, screws, grower

Code

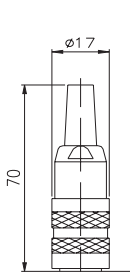
PKIT009



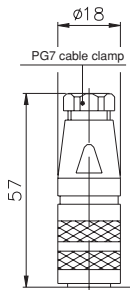
CON002 - IP40 Protection
(3 pole Female connector)



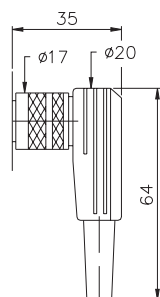
CON006 - IP65 Protection
(DIN43650 4 pole Female connector)



CON011 - IP40 Prot.
(DIN43322 - 5 pole Female conn.)



CON012 - IP67 Prot.
(DIN43322 - 5 pole Female conn.)

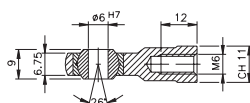
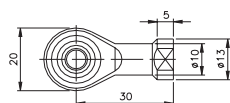


CON013 - IP40 Prot.
(DIN43322 - 5 pole Female conn.)

Extraction length of the connector 10mm.

Coupling ball-joint

PKIT 015



ORDER CODE

Displacement transducer

LT

3 pole connector output	H
4 pole connector output DIN43650 ISO4400	M
5 pole connector output DIN43322	B
3 pole PVC cable output 3x0,25 1m	F

Model

Standard version IP60	S
Version IP65	P

If requested, it is possible to supply models with non-standard mechanical and/or electrical features

Example: **LT - M - 275 - S**

Displacement transducer model LT, 4 pole connector output DIN 43650 - ISO 4400, useful electrical stroke (C.E.U.) 275mm, standard version IP60.

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cod. 84857-08/01



Main features

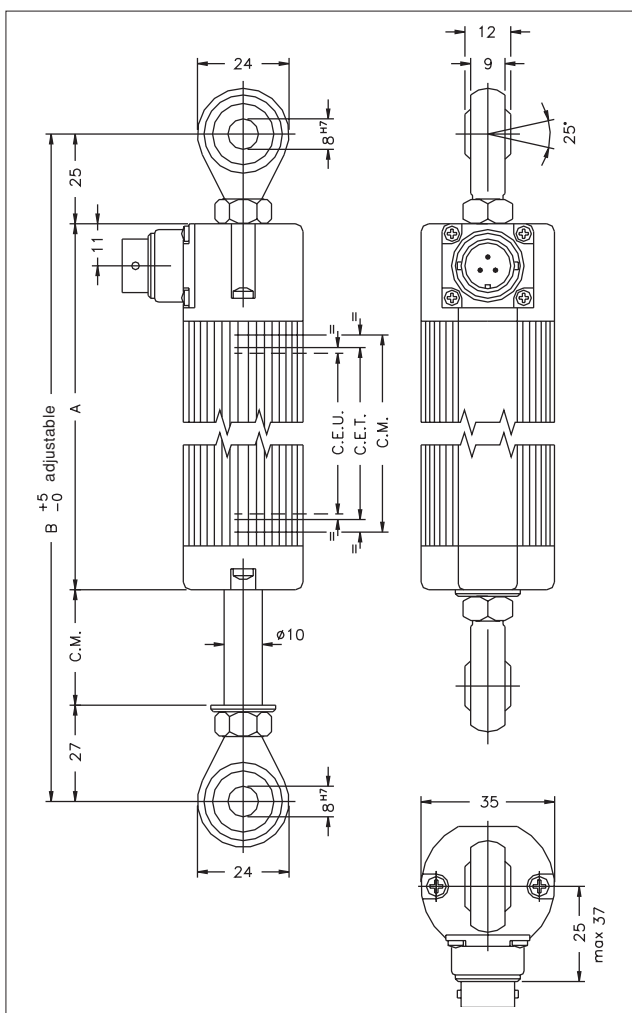
- 50 to 750 mm. stroke
- Mechanical fixing and selfaligning linkage using 2 ball-joints
- Maximum angular movement up to $\pm 30^\circ$
- Independent linearity $\pm 0,05\%$
- Repetibility 0,01 mm.
- Infinite resolution
- No variation of electrical signal outside theoretical electrical stroke
- Displacement speed up to 5 m/s
- Working temperature: $-30...+100^\circ\text{C}$
- Electrical connections:
PC H 3-pole connector
PC M 4-pole connector to standard DIN43650-ISO4400
PC B 5-pole connector (DIN43322)
PC F 3-pole screened cable (1 m length)
- Life duration: $> 25 \times 10^6$ meters or $> 100 \times 10^6$ operations, whichever is the smaller (within C.E.U.)
- Grade of protection IP65

TECHNICAL DATA

Useful electrical stroke (C.E.U.)	50/100/130/150/175/200/225/275/300/375/400/450/500/600/750
Independent linearity (within C.E.U.)	$\pm 0,05\%$
Displacement speed	≤ 5 m/s
Displacement force	≤ 10 N
Vibrations	5...2000Hz, $A_{\text{max}} = 0,75$ mm $a_{\text{max}} = 20$ g
Shock	50 g, 11ms.
Tolerance on resistance	$\pm 20\%$
Recommended cursor current	$< 0,1 \mu\text{A}$
Maximum cursor current	10mA
Maximum applicable voltage	60V
Electrical isolation	$> 100\text{M}\Omega$ at 500V~, 1bar, 2s
Dielectric strength	$< 100 \mu\text{A}$ at 500V~, 50Hz, 2s, 1bar
Dissipation at 40°C (0W at 120°C)	3W
Temp. Coeffi. of the resistance	$-200 \pm 200\text{ppm}/^\circ\text{C}$
Actual Temperature Coefficient of the output voltage	$< 1,5\text{ppm}/^\circ\text{C}$
Working temperature	$-30...+100^\circ\text{C}$
Storage temperature	$-50...+120^\circ\text{C}$
Case material	Anodised aluminium Nylon 66 GF 40
Control rod material	Stainless steel AISI 303
Fixing	2 selfloading and selfaligning ball-joints

Important: all the data reported in the catalogue linearity, lifetime, temperature coefficient are valid for a sensor utilization as a ratiometric device with a max current across the cursor $I_c \leq 0.1 \mu\text{A}$.

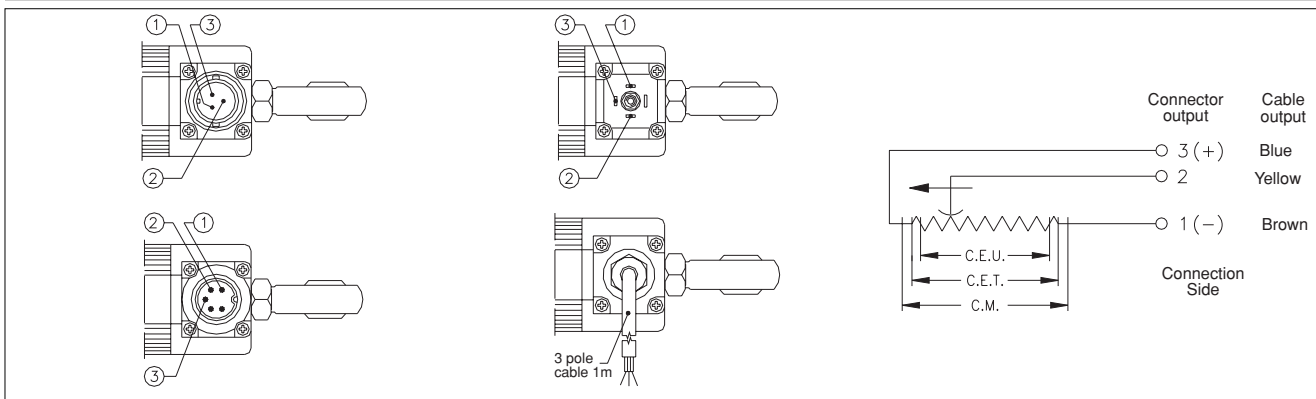
MECHANICAL DIMENSIONS



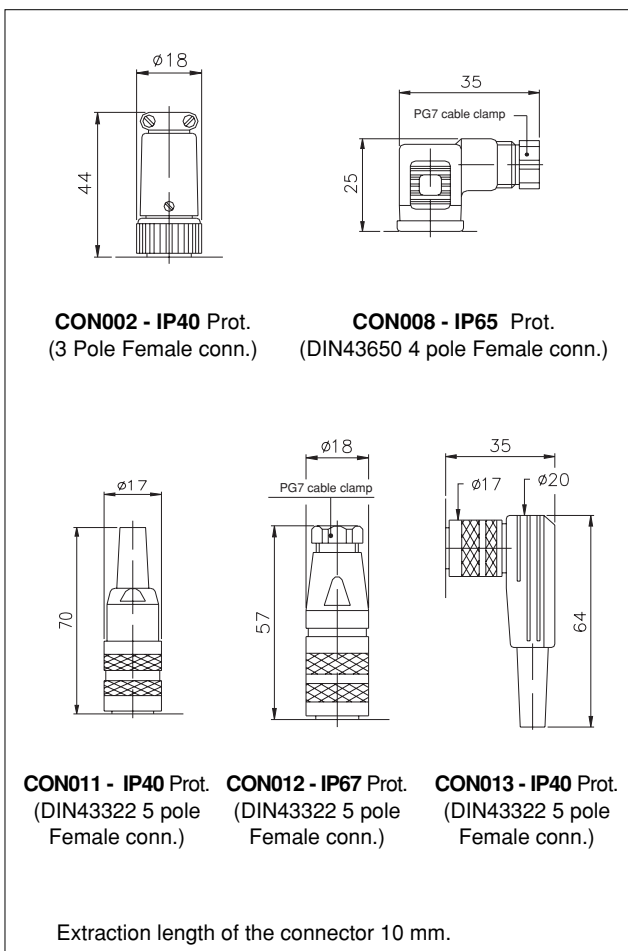
MECHANICAL / ELECTRICAL DATA

MODEL		50	100	130	150	175	200	225	275	300	375	400	450	500	600	750
Useful electrical stroke (C.E.U.) +3/-0	mm	50	100	130	150	175	200	225	275	300	375	400	450	500	600	750
Theoretical electrical stroke (C.E.T.) ± 1	mm	C.E.U. + 3					C.E.U. + 4					380	406	457	508	762
Resistance (C.E.T.)	kΩ	5					5					5	5	5	5	10
Mechanical stroke (C.M.)	mm	C.E.U. + 9					C.E.U. + 10					386	412	463	518	772
Case length (A)	mm	C.E.U. + 129					C.E.U. + 130					512	538	589	664	918
Min. distance between ball-joints (B)	mm	C.E.U. + 181					C.E.U. + 182					564	590	641	716	970

ELECTRICAL CONNECTIONS



OPTIONAL ACCESSORIES



ORDER CODE

Displacement transducer

PC

3-pole connector output	H
4-pole connector output DIN43650 ISO4400	M
5-pole connector output DIN45322	B
3-pole PVC cable output 3x0,25 1m	F

Model

If requested, it is possible to supply models with non-standard mechanical and/or electrical features.

Example: **PC - M - 275**

Displacement transducer model PC, 4 pole connector output DIN43650 - ISO 4400, useful electrical stroke (C.E.U.) 275mm.

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cod.84863-08/01



Main features

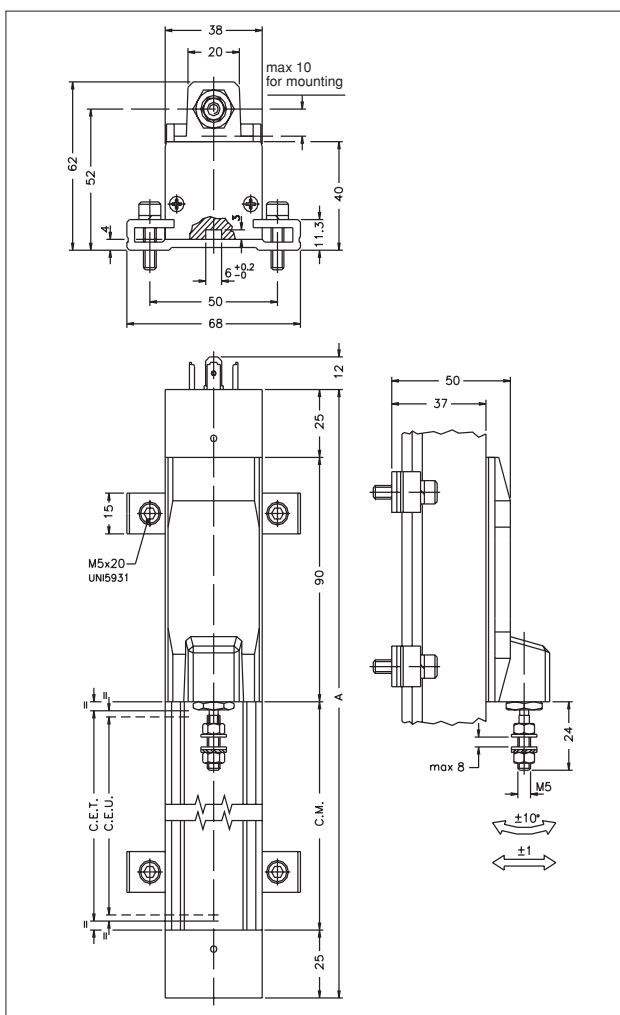
- 100 to 2000 mm. stroke
- Mechanical linkage using joint with take up of play, M5 thread
- Independent linearity up to $\pm 0,05\%$
- Repetibility 0,01 mm.
- Infinite resolution
- No variation of electrical signal outside theoretical electrical stroke
- Displacement speed up to:
4 m/s PK L version
10 m/s PK H version
- Working temperature: $-30...+100^{\circ}\text{C}$
- Electrical connections:
PK M 4-pole connector to standard DIN43650 ISO4400
PK B 5-pole connector (DIN43322)
- Life duration: $> 25 \times 10^6$ meters or $> 100 \times 10^6$ operations, whichever is the smaller (within C.E.U.)
- Grade of protection IP40

TECHNICAL DATA

Useful electrical stroke (C.E.U.)	100/130/150/200/225/300/400/450 500/600/750/900/1000/1250/1500 1750/2000
Independent linearity (within C.E.U.)	$\pm 0,1\%$ from 100 to 400 $\pm 0,05$ from 450 to 2000
Displacement speed	≤ 4 m/s PK L - ≤ 10 m/s PK H
Displacement force	≤ 1.2 N
Vibrations	5...2000Hz, $A_{max} = 0,75$ mm $a_{max} = 20$ g
Shock	50 g, 11ms.
Acceleration operative	200 m/s ² max (20g)
Tolerance on resistance	$\pm 20\%$
Recommended cursor current	$< 0,1 \mu\text{A}$
Maximum cursor current	10mA
Maximum applicable voltage	60V
Electrical isolation	$> 100\text{M}\Omega$ at 500V~, 1bar, 2s
Dielectric strength	$< 100 \mu\text{A}$ at 500V~, 50Hz, 2s, 1bar
Dissipation at 40°C (0W at 120°C)	3W
Temp. Coeff. of the resistance	$-200 \pm 200\text{ppm}/^{\circ}\text{C}$
Actual Temperature Coefficient of the output voltage	$< 1,5\text{ppm}/^{\circ}\text{C}$
Working temperature	$-30...+100^{\circ}\text{C}$
Storage temperature	$-50...+120^{\circ}\text{C}$
Case material	Anodised aluminium Nylon 66 GF 40
Cursor block material	Nylon 66 GF 40 Latilub 73/13
Fixing	Brackets with variable longitudinal axis

Important: all the data reported in the catalogue linearity, lifetime, temperature coefficient are valid for a sensor utilization as a ratiometric device with a max current across the cursor $I_c \leq 0.1 \mu\text{A}$.

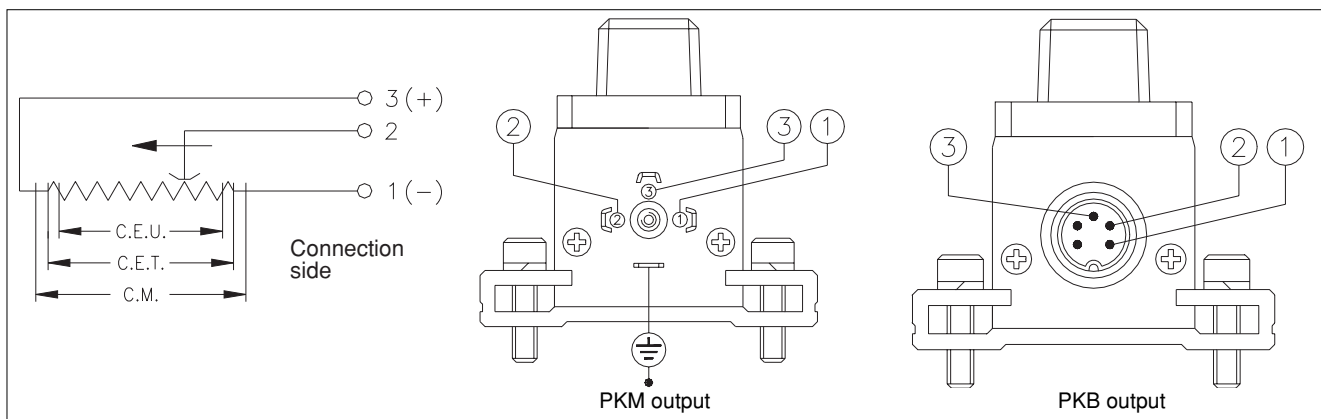
MECHANICAL DIMENSIONS



MECHANICAL / ELECTRICAL DATA

MODEL		100	130	150	200	225	300	400	450	500	600	750	900	1000	1250	1500	1750	2000
Useful electrical stroke (C.E.U.) +3/-0	mm	100	130	150	200	225	300	400	450	500	600	750	900	1000	1250	1500	1750	2000
Theoretical electrical stroke (C.E.T.) ±1	mm	103	133	153	204	229	305	406	458	509	611	763	915	1017	1271	1521	1771	2021
Resistance (C.E.T.)	kΩ	5					10					20						
Mechanical stroke (C.M.)	mm	113	143	163	214	239	315	416	468	519	621	773	925	1027	1281	1531	1781	2031
Case length (A)	mm	253	283	303	354	379	455	556	608	659	761	913	1065	1167	1421	1671	1921	2171

ELECTRICAL CONNECTIONS



ACCESSORIES

STANDARD ACCESSORIES

Fixing kit for PK from 100 to 900:
4 brackets, screws, grower

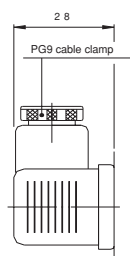
Code

PKIT010

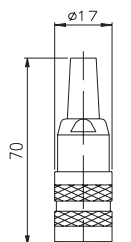
Fixing kit for PK from 1000 to 2000:
3 brackets, screws, grower

PKIT011

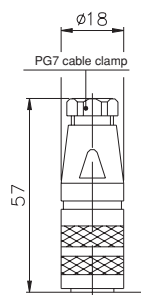
OPTIONAL ACCESSORIES



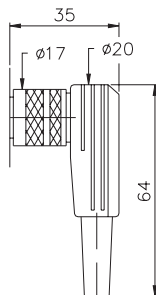
CON006 - IP65 Prot.
(DIN43650 - 4 pole
Female connector)



**CON011
IP40 Prot.**
(DIN43322
5 pole Female
connector)



CON012 - IP67 Prot.
(DIN43322 - 5 pole Female
connector)



CON013 - IP40 Prot.
(DIN43322 - 5 pole Female
connector)

Extraction length of the connector 10 mm.

ORDER CODE

Displacement transducer

PK

4-pole connector output
DIN43650-ISO4400

M

5-pole connector output
DIN43322

B

Model

Displacement speed
up to 4m/s

L

Displacement speed
up to 10m/s

H

If requested, it is possible to supply
models with non-standard mechanical
and/or electrical features

Example: **PK - M - 275 - L**

Displacement transducer model PK, 4-pole connector output
DIN 43650 -9 ISO 4400, useful electrical stroke (C.E.U.)
275mm, displacement speed up to 4 m/s.

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cod. 84869-08/01



- 25 to 150 mm stroke.
- Mechanical linkage using joint with take up of play, M4 thread
- Independent linearity up to $\pm 0,05\%$
- Infinite resolution
- No variation of electrical signal outside theoretical electrical stroke
- Displacement speed up to 5 m/s
- Working temperature: -30...+100°C
- Electrical connections:
PA1 F 3 wire 1 m. screened cable
PA1 C 5 pole connector 1 m. (DIN 43322)
- Life duration: > 100x10⁶ operations (within C.E.U.)
- Grade of protection IP40

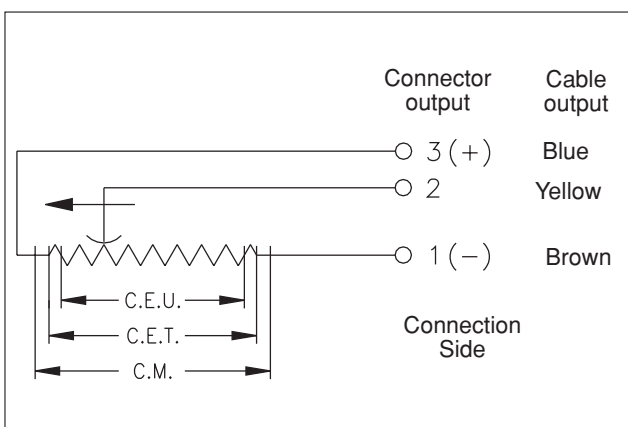
Useful electrical stroke (C.E.U.)	25/50/75/100/125/150
Independent linearity (within C.E.U.)	see table
Displacement speed	≤ 5 m/s
Displacement force	≤ 1.2 N
Vibrations	5...2000Hz, Amax =0,75 mm amax. = 20 g
Shock	50 g, 11 ms.
Tolerance on resistance	± 20%
Recommended cursor current	< 0,1 µA
Maximum cursor current	10mA
Maximum applicable voltage	see table
Electrical isolation	>100MΩ at 500V=, 1bar, 2s
Dielectric strength	< 100 µA at 500V~, 50Hz, 2s, 1bar
Dissipation at 40°C (0W at 120°C)	see table
Temp. Coeff. of the resistance	-200 ± 200ppm/°C
Actual Temperature Coefficient of the output voltage	< 1,5ppm/°C
Working temperature	-30...+100°C
Storage temperature	-50...+120°C
Case material	Anodised aluminium Nylon 66 GV 40
Control rod material	Stainless steel AISI 303
Fixing	Brackets with variable longitudinal axe

Important: all the data reported in the catalogue linearity, lifetime, temperature coefficient are valid for a sensor utilization as a ratiometric device with a max current across the cursor $I_c \leq 0.1 \mu A$.

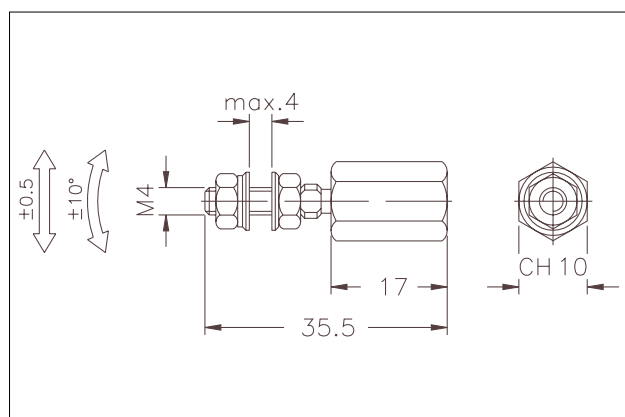
MECHANICAL / ELECTRICAL DATA

MODEL		25	50	75	100	125	150
Useful electrical stroke (C.E.U.) +1/-0	mm	25	50	75	100	125	150
Theoretical electrical stroke (C.E.T.) ±1	mm	C.E.U. +1					
Resistance (sulla C.E.T.)	kΩ	1	5	5	5	5	5
Independent linearity (within C.E.U.)	± %	0,2	0,1	0,1	0,1	0,05	0,05
Dissipation at 40°C (0W at 120°C)	W	0,6	1,2	1,8	2,5	3	3,6
Maximum applicable voltage	V	25	60				
Mechanical stroke (C.M.)	mm	C.E.U. +5					
Case length (A)	mm	C.E.U. +49,5					
Total length (B)	mm	113,2	163,2	213,2	263,2	313,2	363,2

ELECTRICAL CONNECTIONS



COUPLING JOINT



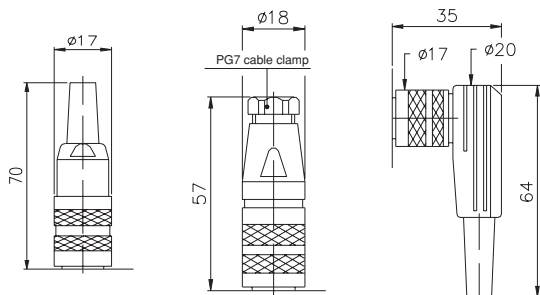
ACCESSORIES

STANDARD ACCESSORIES

Fixing kit for PA1:
4 brackets, M4x10 screws, grower

Coupling joint

OPTIONAL ACCESSORIES



Extraction length of the connector 10mm

ORDER CODE

Displacement transducer

PA1

Cable output	F
Connector output DIN 43322	C

Model

3 pole PVC cable
3x0.25 1m.

Connector output

If requested, it is possible to supply models with non-standard mechanical and/or electrical features

Example: PA1 - C - 100

Displacement transducer model PA1, 5 pole connector output, useful electrical stroke (C.E.U.) 100mm

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cod. 84905-08/01



- 25 to 150 mm. stroke
- Mechanical linkage using joint with take up of play, M4 thread
- Independent linearity up to $\pm 0,05\%$
- Infinite resolution
- No variation of electrical signal outside theoretical electrical stroke
- Displacement speed up to 10 m/s
- Working temperature: -30...+100°C
- Electrical connections:
PY1 F 3 wire 1m screened cable
PY1 C 5-pole connectors DIN43322
- Life duration: > 100x10⁶ operations (within C.E.U.)
- Double support of the control rod
- Grade of protection IP40

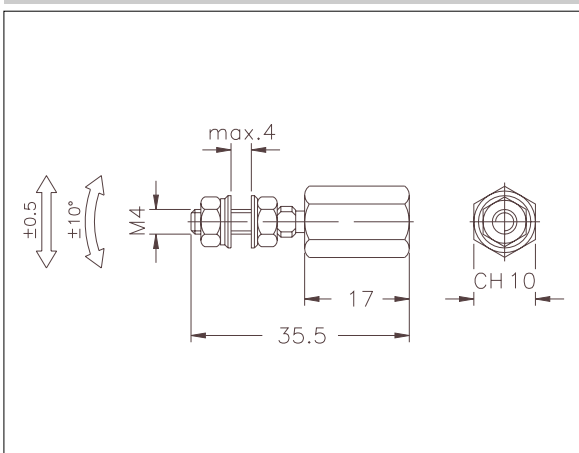
Useful electrical stroke (C.E.U.)	25/50/75/100/150
Independent linearity (within C.E.U.)	see table
Displacement speed	≤ 10 m/s
Displacement force	≤ 0.30N
Vibrations	5...2000Hz, Amax =0,75 mm amax. = 20 g
Shock	50 g, 11ms.
Tolerance on resistance	± 20%
Recommended cursor current	< 0,1 µA
Maximum cursor current	10mA
Maximum applicable voltage	see table
Electrical isolation	>100MΩ at 500V=, 1bar, 2s
Dielectric strength	< 100 µA at 500V~, 50Hz, 2s, 1bar
Dissipation at 40°C (0W at 120°C)	see table
Temp. Coeff. of the resistance	-200 ± 200ppm/°C
Actual Temperature Coefficient of the output voltage	< 1,5ppm/°C
Working temperature	-30...+100°C
Storage temperature	-50...+120°C
Case material	Anodised aluminium Nylon 66 GF 40
Control rod material	Stainless steel AISI 303
Fixing	Brackets with variable longitudinal axis

Important: all the data reported in the catalogue linearity, lifetime, temperature coefficient are valid for a sensor utilization as a ratiometric device with a max current across the cursor $I_c \leq 0.1 \mu A$.

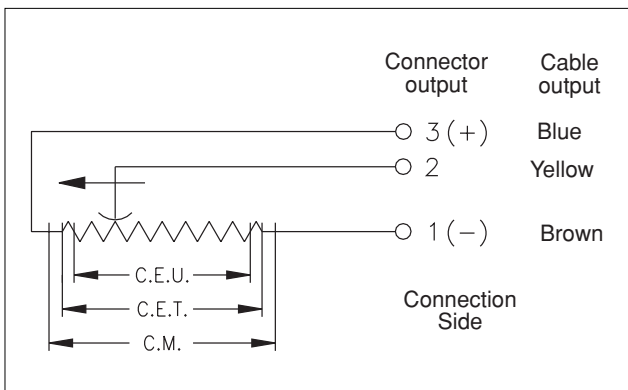
MECHANICAL / ELECTRICAL DATA

MODEL		25	50	75	100	150
Useful electrical stroke (C.E.U.) +3/-0	mm	25	50	75	100	150
Theoretical electrical stroke (C.E.T.) ±1	mm	C.E.U. + 1				
Resistance (C.E.T.)	kΩ	1	5	5	5	5
Independent linearity (within C.E.U.)	± %	0,2	0,1	0,1	0,1	0,05
Dissipation at 40° (0W at 120°C)	W	0,6	1,2	1,8	2,5	3,6
Maximum applicable voltage	V	25	60			
Mechanical stroke (C.M.)	mm	C.E.U. + 5				
Case length (A)	mm	C.E.U. + 38				
Total length (B)	mm	107	157	207	257	357

COUPLING JOINT



ELECTRICAL CONNECTIONS



ORDER CODE

Displacement transducer **PY1**

Cable output	F
Connector output DIN43322	C

Model

3-pole PVC cable output 3x0,25 1meter	S
Connector output	----

If requested, it is possible to supply models with non-standard mechanical and/or electrical features

Example: PY1 - C - 100
Displacement transducer model PY1, 5-pole connector output, useful electrical stroke (C.E.U.) 100mm.

ACCESSORIES

STANDARD ACCESSORIES

Fixing kit for PY1
4 brackets, M4x10 screws, grower **PKIT005**

Coupling joint **PKIT020**

OPTIONAL ACCESSORIES

CON011 - IP40 Prot. (5 pole Female conn.)
CON012 - IP67 Prot. (5 pole Female conn.)
CON013 - IP40 Prot. (5 pole Female conn.)

Extraction length of the connector 10mm.

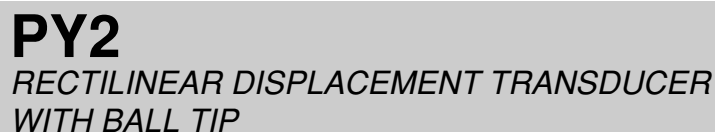
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cod. 84911-08/01



- 10 to 50 mm. stroke
- Double support of the control rod and return spring
- Tip with M2.5 thread and stainless steel ball
- Independent linearity up to $\pm 0,1\%$
- Infinite resolution
- No variation of electrical signal outside theoretical electrical stroke
- Displacement speed up to 10 m/s
- Working temperature: $-30...+100^{\circ}\text{C}$
- Electrical connections:
PY2 F 3 wire 1m screened cable
PY2 C 5-pole connector DIN43322
- Life duration: $> 100 \times 10^6$ operations (within C.E.U.)
- Grade of protection IP40

Useful electrical stroke (C.E.U.)	10/25/50
Independent linearity (within C.E.U.)	see table
Displacement speed	≤ 10 m/s
Displacement force	≤ 4N
Vibrations	5...2000Hz, Amax =0,75 mm amax. = 20 g
Shock	50 g, 11ms.
Tolerance on resistance	± 20%
Recommended cursor current	< 0,1 µA
Maximum cursor current	10mA
Maximum applicable voltage	see table
Electrical isolation	>100MΩ at 500V=, 1bar, 2s
Dielectric strength	< 100 µA at 500V~, 50Hz, 2s, 1bar
Dissipation at 40°C (0W at 120°C)	see table
Temp. Coeff. of the resistance	-200 ± 200ppm/°C
Actual Temperature Coefficient of the output voltage	< 1,5ppm/°C
Working temperature	-30...+100°C
Storage temperature	-50...+120°C
Case material	Anodised aluminium Nylon 66 GF 40
Control rod material	Stainless steel AISI 303
Fixing	Brackets with variable longitudinal axis

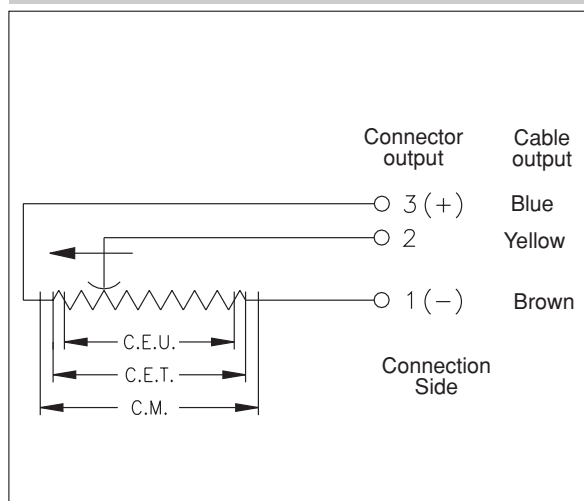
[illegible]

Important: all the data reported in the catalogue linearity, lifetime, temperature coefficient are valid for a sensor utilization as a ratiometric device with a max current across the cursor $I_c \leq 0.1 \mu A$.

MECHANICAL / ELECTRICAL DATA

MODEL		10	25	50
Useful electrical stroke (C.E.U.) +1/-0	mm	10	25	50
Theoretical electrical stroke (C.E.T.) ±1	mm	C.E.U. + 1		
Resistance (C.E.T.)	kΩ	1	1	5
Independent linearity (within C.E.U.)	± %	0,3	0,2	0,1
Dissipation at 40° (0W at 120°C)	W	0,2	0,6	1,2
Maximum applicable voltage	V	14	25	60
Mechanical stroke (C.M.)	mm	C.E.U. + 5		
Case length (A)	mm	C.E.U. + 38		
Tip length (B)	mm	32	32	40
Total length (C)	mm	108	138	196

ELECTRICAL CONNECTIONS



ACCESSORIES

STANDARD ACCESSORIES

Fixing kit for PY2:

4 brackets, M4x10 screws, grower

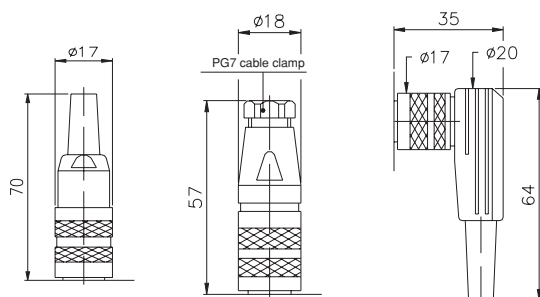
Ball tip

Code

PKIT005

PTAS000

OPTIONAL ACCESSORIES



CON011 - IP40 Prot.
(5 pole Female conn.)

CON012 - IP67 Prot.
(5 pole Female conn.)

CON013 - IP40 Prot.
(5 pole Female conn.)

Extraction length of the connector 10 mm.

ORDER CODE

Displacement transducer

PY2

Cable output

F

Connector output
DIN43322

C

Model

3-pole PVC cable output
3 x 0,25 1m

S

Connector
output

If requested, it is possible to supply
models with non-standard mechanical
and/or electrical features

Example: PY2 - C - 100

Displacement transducer model PY2, 5-pole connector
output, useful electrical stroke (C.E.U.) 50mm.

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cod. 84917-08/01

PY3

RECTILINEAR DISPLACEMENT TRANSDUCER WITH BEARING TIP



Main features

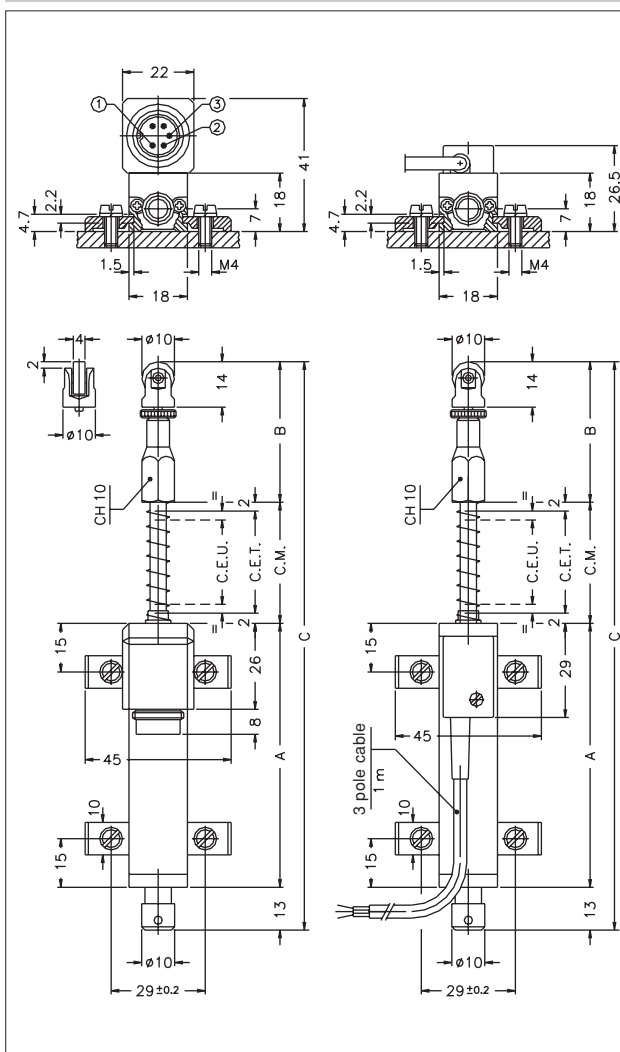
- 25 to 50 mm. stroke
- Double support of the control rod and return spring
- Tip with M2.5 thread and stainless steel precision bearing
- Independent linearity up to $\pm 0,1\%$
- Infinite resolution
- No variation of electrical signal outside theoretical electrical stroke
- Inhibited rotation of the control rod
- Displacement speed up to 10 m/s
- Working temperature: $-30...+100^{\circ}\text{C}$
- Electrical connections:
PY3 F 3-pole 1m. screened cable 1m.
PY3 C 5-pole connector DIN43322
- Life duration: $> 100 \times 10^6$ operations (within C.E.U.)
- Grade of protection IP40

TECHNICAL DATA

Useful electrical stroke (C.E.U.)	25/50
Independent linearity (within C.E.U.)	see table
Displacement speed	≤ 10 m/s
Displacement force	≤ 4 N
Vibrations	5...2000Hz, $A_{max} = 0,75$ mm $a_{max} = 20$ g
Shock	50 g, 11ms.
Tolerance on resistance	$\pm 20\%$
Recommended cursor current	$< 0,1 \mu\text{A}$
Maximum cursor current	10mA
Maximum applicable voltage	see table
Electrical isolation	$> 100\text{M}\Omega$ at 500V~, 1bar, 2s
Dielectric strength	$< 100 \mu\text{A}$ at 500V~, 50Hz, 2s, 1bar
Dissipation at 40°C (0W at 120°C)	see table
Temp. Coeff. of the resistance	$-200 \pm 200\text{ppm}/^{\circ}\text{C}$
Actual Temperature Coefficient of the output voltage	$< 1,5\text{ppm}/^{\circ}\text{C}$
Working temperature	$-30...+100^{\circ}\text{C}$
Storage temperature	$-50...+120^{\circ}\text{C}$
Case material	Anodised aluminium Nylon 66 GF 40
Control rod material	Stainless steel AISI 303
Fixing	Brackets with variable longitudinal axis

Important: all the data reported in the catalogue linearity, lifetime, temperature coefficient are valid for a sensor utilization as a ratiometric device with a max current across the cursor $I_c \leq 0.1 \mu\text{A}$.

MECHANICAL DIMENSIONS



MECHANICAL / ELECTRICAL DATA

MODEL		25	50
Useful electrical stroke (C.E.U.) +1/-0	mm	25	50
Theoretical electrical stroke (C.E.T.) ±1	mm	C.E.U. + 1	
Resistance (C.E.T.)	kΩ	1	5
Independent linearity (within C.E.U.)	± %	0,2	0,1
Dissipation at 40° (0W at 120°C)	W	0,6	1,2
Maximum applicable voltage	V	25	60
Mechanical stroke (C.M.)	mm	C.E.U. + 5	
Case length (A)	mm	C.E.U. + 38	
Tip length (B)	mm	43	51
Total length (C)	mm	149	207

ACCESSORIES

STANDARD ACCESSORIES

Fixing kit for PY3:

4 brackets, M4x10 screws, grower

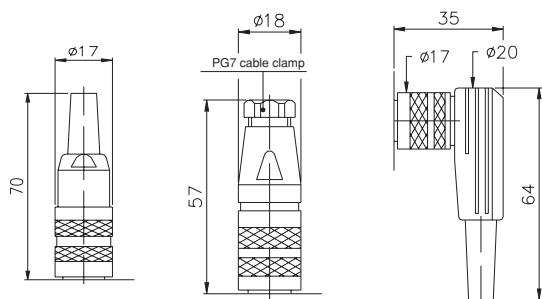
Bearing tip

Code

PKIT005

PTAS001

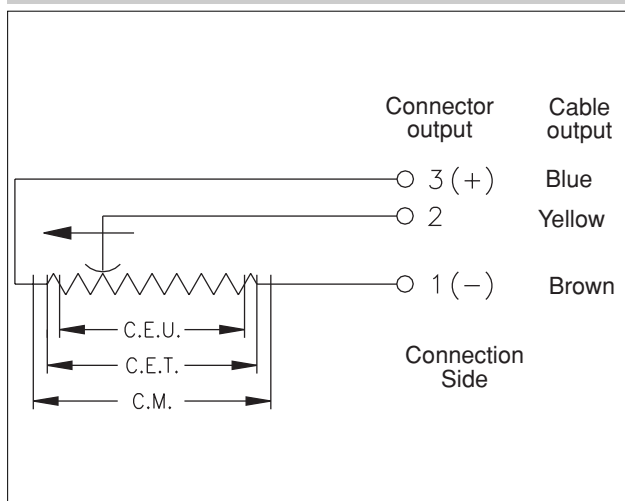
OPTIONAL ACCESSORIES



CON011 - IP40 Prot. (5 pole Female conn.) **CON012 - IP67 Prot.** (5 pole Female conn.) **CON013 - IP40 Prot.** (5 pole Female conn.)

Extraction length of the connector 10 mm.

ELECTRICAL CONNECTIONS



ORDER CODE

Displacement transducer

PY3

Cable output

F

Connector output
DIN43322

C

Model

3-pole PVC cable output
3 x 0,25 1m

S

Connector
output

If requested, it is possible to supply
models with non-standard mechanical
and/or electrical features

Example: **PY3 - C - 50**

Displacement transducer model PY3, 5-pole connector
output, useful electrical stroke (C.E.U.) 50mm.

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cod. 84923-08/01

PZ12

RECTILINEAR DISPLACEMENT TRANSDUCER WITH CYLINDRICAL CASE



Main features

- 25 to 150 mm. stroke
- Mechanical fixing using brackets, selfaligning ball-joints or flange
- Independent linearity up to $\pm 0,05\%$
- Infinite resolution
- No variation of electrical signal outside theoretical electrical stroke
- Displacement speed up to 10 m/s
- Working temperature: $-30...+100^{\circ}\text{C}$
- Electrical connection: 3-pole screened cable (1m length)
- Life duration: $> 25 \times 10^6$ meters or $> 100 \times 10^6$ operations whichever is the smaller (within C.E.U.)
- Grade of protection IP60

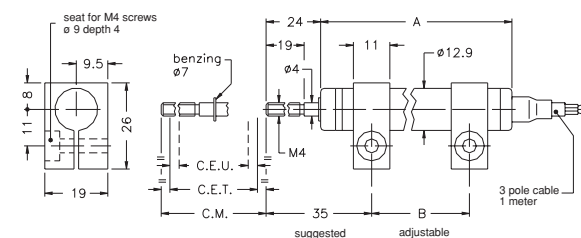
TECHNICAL DATA

Useful electrical stroke (C.E.U.)	25/50/75/100/125/150
Independent linearity (within C.E.U.)	see table
Displacement speed	≤ 10 m/s
Displacement force	$\leq 0.5\text{N}$
Vibrations	5...2000Hz, $A_{\text{max}} = 0,75$ mm $a_{\text{max}} = 20$ g
Shock	50 g, 11ms.
Tolerance on resistance	$\pm 20\%$
Recommended cursor current	$< 0,1 \mu\text{A}$
Maximum cursor current	10mA
Maximum applicable voltage	see table
Electrical isolation	$> 100\text{M}\Omega$ at 500V~, 1bar, 2s
Dielectric strength	$< 100 \mu\text{A}$ at 500V~, 50Hz, 2s, 1bar
Dissipation at 40°C (0W at 120°C)	see table
Temp. Coeff. of the resistance	$-200 \pm 200\text{ppm}/^{\circ}\text{C}$
Actual Temperature Coefficient of the output voltage	$< 1,5\text{ppm}/^{\circ}\text{C}$
Working temperature	$-30...+100^{\circ}\text{C}$
Storage temperature	$-50...+120^{\circ}\text{C}$
Case material	Anodised aluminium Nylon 66 GV 40
Control rod material	Stainless steel AISI 303
Fixing	Brackets, selfaligning ball-joints or flange

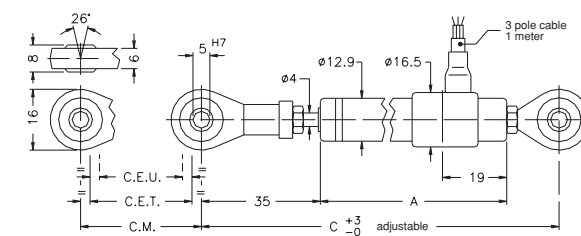
Important: all the data reported in the catalogue linearity, lifetime, temperature coefficient are valid for a sensor utilization as a ratiometric device with a max current across the cursor $I_c \leq 0.1 \mu\text{A}$.

MECHANICAL DIMENSIONS

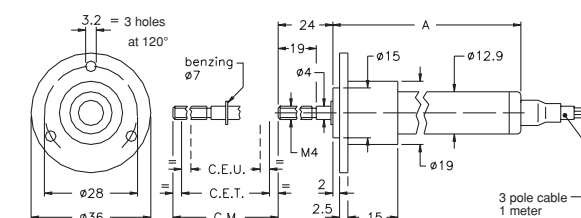
PZ12-S



PZ12-A



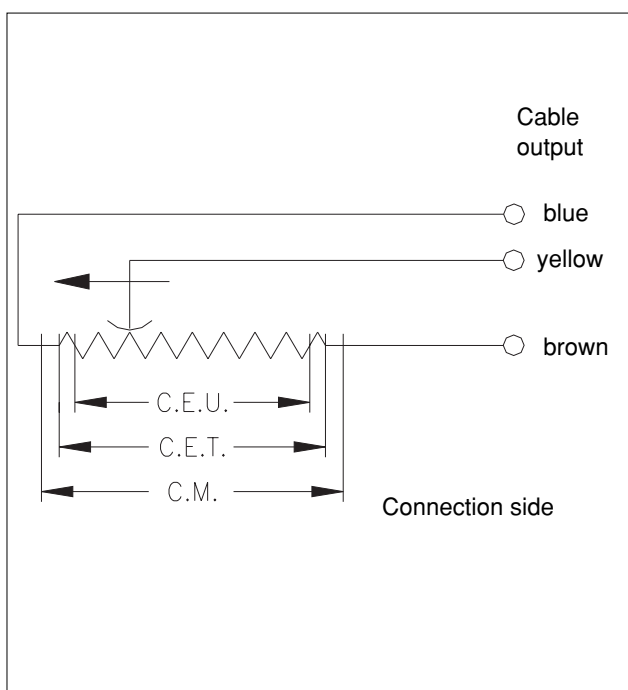
PZ12-F



MECHANICAL / ELECTRICAL DATA

MODEL			25	50	75	100	125	150
Useful electrical stroke (C.E.U.) + 1 / -0		mm	25	50	75	100	125	150
Theoretical electrical stroke (C.E.T.) ± 1		mm	C.E.U. +1					
Resistance (C.E.T.)		kΩ	1	2	3	4	5	6
Independent linearity (within C.E.U.)		± %	0,2	0,1	0,1	0,1	0,05	0,05
Dissipation at 40°C (0W at 120°C)		W	0,5	1	1,5	2	2,5	3
Maximum applicable voltage		V	20	40	60			
Mechanical stroke (C.M.)		mm	C.E.U. +5					
Case length (A)	mod. PZ12 - S	mm	74,5	99,5	124,5	149,5	174,5	199,5
	mod. PZ12 - A	mm	102	127	152	177	202	227
	mod. PZ12 - F	mm	74,5	99,5	124,5	149,5	174,5	199,5
Recommended distance between brackets (B)		mm	42	67	92	117	142	167
Minimum distance between ball-joints (C)		mm	153	178	203	228	253	278
Weight	mod. PZ12 - S	g	45	55	65	75	85	95
	mod. PZ12 - A	g	70	80	90	100	110	120
	mod. PZ12 - F	g	60	70	80	90	100	110

ELECTRICAL CONNECTIONS



STANDARD ACCESSORIES

	Code
2 mounting brackets for PZ12-S	STA074

ORDER CODE

Displacement transducer **PZ12**

Mounting by brackets	S
Mounting by selfaligning ball-joints	A
Mounting by flange	F

Model

If requested, it is possible to supply models with non-standard mechanical and/or electrical features

Example: **PZ12 - S - 25**
 Displacement transducer model PZ12, mounting by brackets, useful electrical stroke (C.E.U.) 25mm

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cod. 84875-08/01

PZ34

RECTILINEAR DISPLACEMENT TRANSDUCER WITH CYLINDRICAL CASE



Main features

- 25 to 250 mm. stroke
- Mechanical fixing using brackets, selfaligning ball-joints or flange
- Independent linearity up to $\pm 0,05\%$
- Infinite resolution
- No variation of electrical signal outside theoretical electrical stroke
- Displacement speed 10 m/s
- Working temperature: $-30...+100^{\circ}\text{C}$
- Electrical connection: 3-pole screened cable (1m length)
- Life duration: $> 25 \times 10^6$ meters or $> 100 \times 10^6$ operations, whichever is the smaller (within C.E.U.)
- Grade of protection IP60

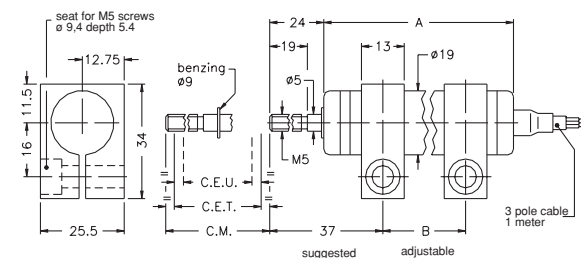
CARATTERISTICHE TECNICHE

Useful electrical stroke (C.E.U.)	25/50/75/100/125/150/200/250
Independent linearity (within C.E.U.)	see table
Displacement speed	≤ 10 m/s
Displacement force	$\leq 0.5\text{N}$
Vibrations	5...2000Hz, $A_{\text{max}} = 0,75$ mm $a_{\text{max}} = 20$ g
Shock	50 g, 11ms.
Tolerance on resistance	$\pm 20\%$
Recommended cursor current	$< 0,1 \mu\text{A}$
Maximum cursor current	10mA
Maximum applicable voltage	see table
Electrical isolation	$> 100\text{M}\Omega$ at 500V~, 1bar, 2s
Dielectric strength	$< 100 \mu\text{A}$ at 500V~, 50Hz, 2s, 1bar
Dissipation at 40°C (0W at 120°C)	see table
Temp. Coeff. of the resistance	$-200 \pm 200\text{ppm}/^{\circ}\text{C}$
Actual Temperature Coefficient of the output voltage	$< 1,5\text{ppm}/^{\circ}\text{C}$
Working temperature	$-30...+100^{\circ}\text{C}$
Storage temperature	$-50...+120^{\circ}\text{C}$
Case material	Anodised aluminium Nylon 66 GV 40
Control rod material	Stainless steel AISI 303
Fixing	Brackets, selfaligning ball-joints or flange

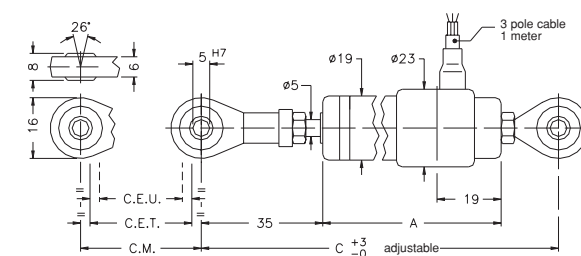
Important: all the data reported in the catalogue linearity, lifetime, temperature coefficient are valid for a sensor utilization as a ratiometric device with a max current across the cursor $I_c \leq 0.1 \mu\text{A}$.

MECHANICAL DIMENSIONS

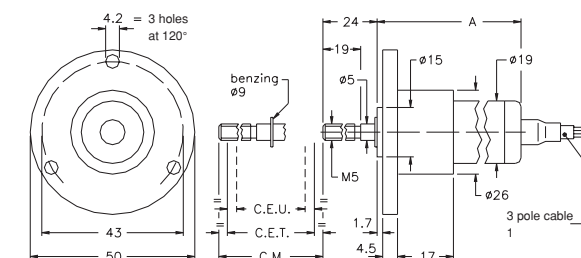
PZ34-S



PZ34-A



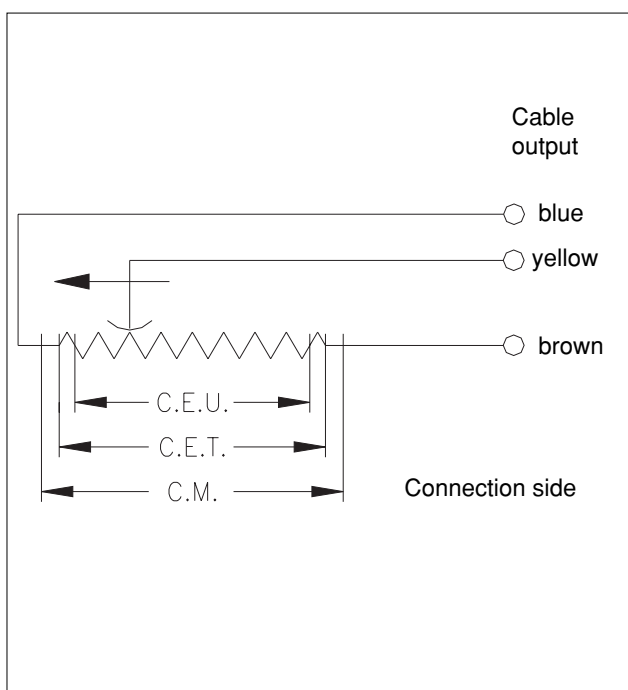
PZ34-F



MECHANICAL / ELECTRICAL DATA

MODEL			25	50	75	100	125	150	200	250
Useful electrical stroke (C.E.U.) +1/-0		mm	25	50	75	100	125	150	200	250
Theoretical electrical stroke (C.E.T.) ±1		mm	C.E.U. +1							
Resistance (C.E.T.)		kΩ	1	2	3	4	5	6	8	10
Independent linearity (within C.E.U.)		± %	0,2	0,1	0,1	0,1	0,05	0,05	0,05	0,05
Dissipation at 40°C (0W at 120°C)		W	0,8	1,6	2,6	3				
Maximum applicable voltage		V	20	40	60					
Mechanical stroke (C.M.)		mm	C.E.U. +5							
Case length (A)	mod. PZ34 - S	mm	83,5	108,5	133,5	158,5	183,5	208,5	258,5	308,5
	mod. PZ34 - A	mm	110	135	160	185	210	235	285	335
	mod. PZ34 - F	mm	83,5	108,5	133,5	158,5	183,5	208,5	258,5	308,5
Recom. distance between brackets (B)		mm	47	72	97	122	147	172	222	272
Min. distance between ball-joints (C)		mm	163	188	213	238	263	288	338	388
Weight	mod. PZ34 - S	g	90	105	130	160	175	190	215	245
	mod. PZ34 - A	g	110	125	150	180	195	210	235	260
	mod. PZ34 - F	g	100	115	140	170	185	200	225	255

ELECTRICAL CONNECTIONS



STANDARD ACCESSORIES

	Code
2 mounting brackets for PZ34-S	STA075

ORDER CODE

Displacement transducer **PZ34**

Mounting by brackets	S
Mounting by selfaligning ball-joints	A
Mounting by flange	F

Model

If requested, it is possible to supply models with non-standard mechanical and/or electrical features

Example: **PZ34 - F - 125**
Displacement transducer model PZ34, mounting by flange, useful electrical stroke (C.E.U.) 125mm.

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cod. 84881-08/01



RECTILINEAR DISPLACEMENT TRANSDUCER WITH MAGNETIC
DRAG *Patent Pending*



Main features

- 50 to 1000 mm. strokes
- *Cursor magnetic drag*
- *Independent linearity $\pm 0,05\%$*
- *Repeatability: 0.08 mm*
- *Hysteresis: 0.25 mm*
- *Infinite Resolution*
- *No variation of electrical output signal outside theoretical electrical stroke*
- *Working temperature: -30...+100°C*
- *Electrical connection: 3-pole polyurethane screened cable with high flexibility (1m length)*
- *Lifetime: > 25x10⁶ meters or >100x10⁶ operations, whichever is the smallest (within C.E.U.)*
- *IP67 waterproof, (IEC 60529)*
- *Suitable for pneumatic applications with working pressures max. 20bar, 50bar peak*

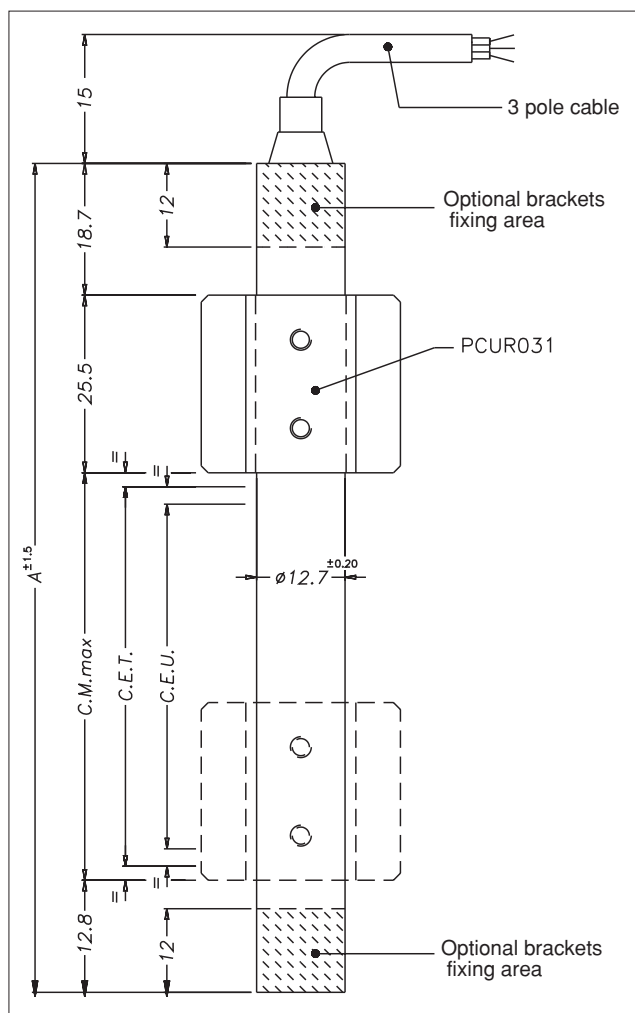
Rectilinear potentiometric displacement transducer without dragging shaft; completely waterproof (IP67); designed to work whether in wet environments or temporarily submerged (IEC 60529). The PME series is characterised by an external magnetic actuator coupled with an internal measurement cursor. The magnetic cursor substitutes the dragging tree used in the traditional displacement transducers; by this way, the overall dimensions are smaller.

TECHNICAL DATA

Useful electrical stroke (C.E.U.)	50 to 1000 mm
Independent linearity (within C.E.U.)	see table
Displacement speed	≤ 5 m/s
Max. acceleration	≤ 10m/s ² displacement
DIN vibration IEC 68T2-6	12g, 10...2000Hz
Cursor dragging force	≤ 0,5 N
Shock test DIN IEC68T2-27	50 g, 11ms. single shock
Displacement sensitivity (no hysteresis)	from 0.05 to 0.1 mm
Tolerance on resistance	± 20%
Recommended cursor current	< 0,1 μA
Maximum cursor current in case of bad performances	10mA
Maximum applicable voltage	see table
Electrical isolation	>100MΩ at 500V~, 1bar, 2s
Dielectric strenght	<100 μA at 500V~, 50Hz, 2s, 1bar
Dissipation at 40°C (0W at 120°C)	see table
Enviromental protection	IP 67
Actual temperature coefficient of the output voltage	< 1,5ppm/°C
Working temperature	-30...+100°C
Storage temperature	-50...+120°C

Importante: All the data reported in the catalogue linearity and temperature coefficients are valid for sensor utilization as a ratiometric device with a max. current across the cursor circuit $I_c \leq 0.1 \mu A$.

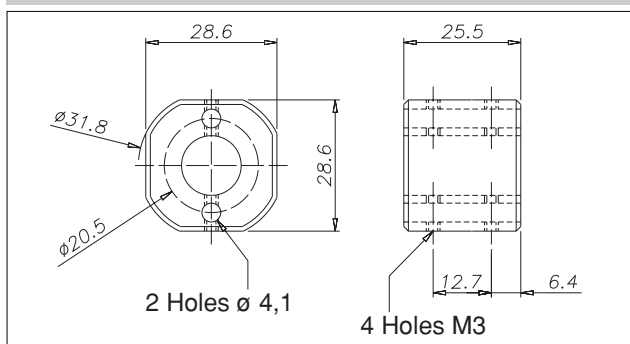
MECHANICAL DIMENSION



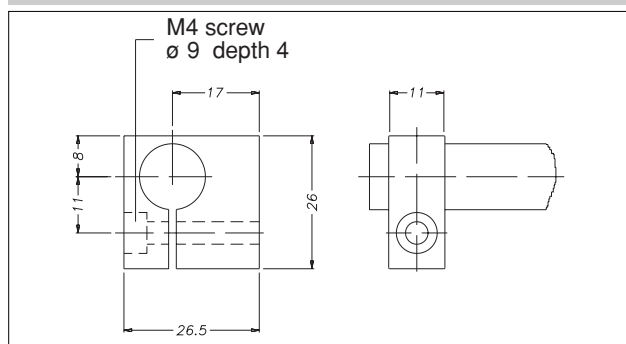
MECHANICAL / ELECTRICAL DATA

MODEL		50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
Useful electrical stroke (C.E.U.) + 1 / -0	mm	Model																			
Theoretical electrical stroke (C.E.T.) ± 1	mm	C.E.U. + 1																			
Resistance (C.E.T.)	kΩ	5						10						20							
Independent linearity (within C.E.U.)	±%	0,1		0,05																	
Dissipation at 40°C (0W at 120°C)	W	1	2	3																	
Max applicable voltage	V	40	60																		
Mechanical stroke (C.M)	mm	C.E.U. + 5																			
Case Lenght (A)	mm	C.E.U. + 61,5																			

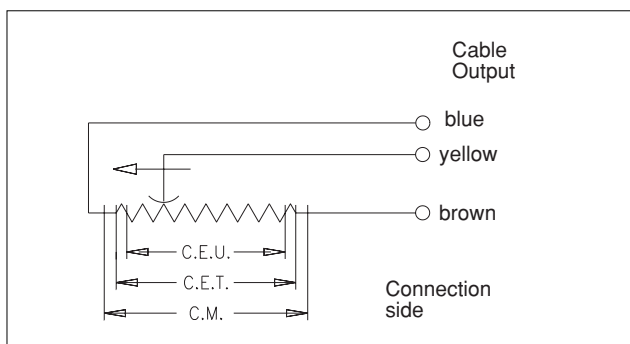
PCUR031 CURSOR



STA001 BRACKETS



ELECTRICAL CONNECTIONS



ORDER CODE

Displacement transducer

PME

12

F

S

Dimension 1/2"

3-pole PVC cable output 3x0,25 1m

Model

Brackets

If requested, it is possible to supply models with non-standard mechanical and/or electrical features

Example: **PME-12-F-400-S 0000-X000-XX-00-XXX**

PME12 model transducer, useful electrical stroke (C.E.U.) 400mm, mounting by brackets.

Included in the delivery

- Displacement Transducer PME series
- N° 2 Fixing brackets
- N° 1 Magnetic cursor

code: **STA001**

code: **PCUR032**

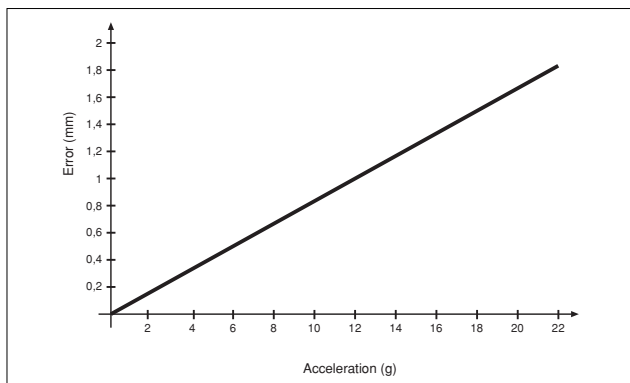
CODE EXTENSION

0 0 0 0 X 0 0 0 X X 0 0 X X X

CABLE LENGTH (1mt F standard version)

F output 00 = 1mt 02 = 2mt 03 = 3mt 04 = 4mt 05 = 5mt
10 = 10mt 15 = 15mt

TRACKING ERROR



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www.gefranonline.com



cod. 84981 -11/01



Main features

- 50 to 1000 mm strokes
- Cursor magnetic drag
- Independent linearity up to $\pm 0,05\%$
- Repeatability: $\leq 0,08$ mm
- Hysteresis: $\leq 0,25$ mm
- Tracking error (see table)
- Infinite resolution
- No variation of electrical output signal outside theoretical electrical stroke
- Working temperature: $-30...+100^{\circ}\text{C}$
- Electrical connection: 3-pole polyurethane screened cable with high flexibility (1m lenght)
- AISI 316 stem and nipple
- Lifetime: $> 25 \times 10^6$ meters or $> 100 \times 10^6$ operations whichever is the smallest (within C.E.U.)
- Max. working pressure 250bar, 400bar peak

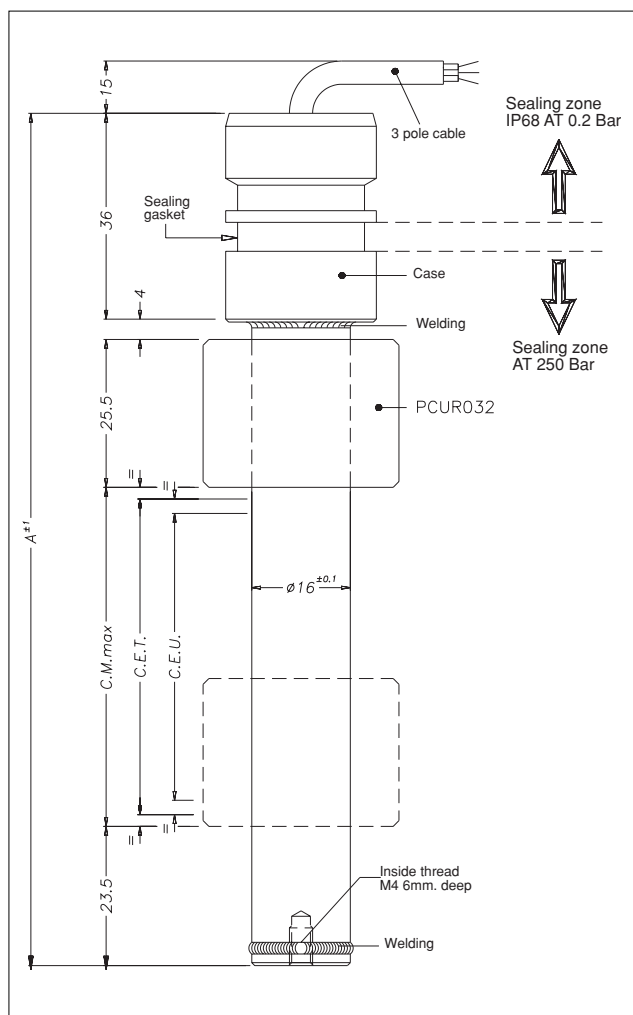
Rectilinear potentiometric displacement transducer without dragging shaft; completely waterproof (IP68); designed to work with high pressure applications (250bar static, 400bar peak) i.e. hydraulic cylinders. The PMI series is characterised by an external magnetic actuator coupled with an internal measurement cursor.

TECHNICAL DATA

Useful electical stroke (C.E.U.)	50 to 1000 mm
Linearità indipendente (within C.E.U.)	see table
Displacement speed	≤ 5 m/s
Max. acceleration	$\leq 10\text{m/s}^2$ displacement
DIN vibration IEC 68T2-6	12g, 10...2000Hz
Cursor dragging force	$\leq 0,5$ N
Shock test DIN IEC68T2-27	50 g, 11ms. single shock
Displacement sensitivity (no hysteresis)	0.05 to 0.1 mm
Tolerance on resistance	$\pm 20\%$
Recommended cursor current	$< 0,1 \mu\text{A}$
Maximum cursor current in case of bad performances	10mA
Maximum applicable voltage	See table
Electrical isolation	$> 100\text{M}\Omega$ at 500V~, 1bar, 2s
Dielectric strenght	$< 100\mu\text{A}$ at 500V~, 50Hz, 2s, 1bar
Dissipation at 40°C (0W at 120°C)	see table
Enviromental protection	IP 68, max. pressure 250 bar, 400 bar peak
Actual temperature coefficient of the output voltage	$< 1,5\text{ppm}/^{\circ}\text{C}$
Working temperature	$-30...+100^{\circ}\text{C}$
Storage temperature	$-50...+120^{\circ}\text{C}$

Important: All the data reported in the catalogue linearity and temperature coefficients are valid for a sensor utilization as a ratiometric device with a max current across the cursor circuit $I_c \leq 0.1 \mu\text{A}$.

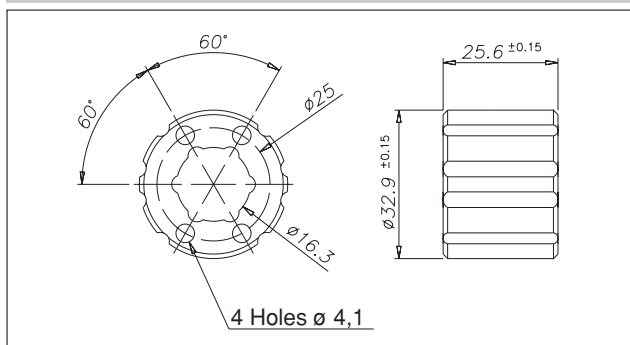
MECHANICAL DIMENSION



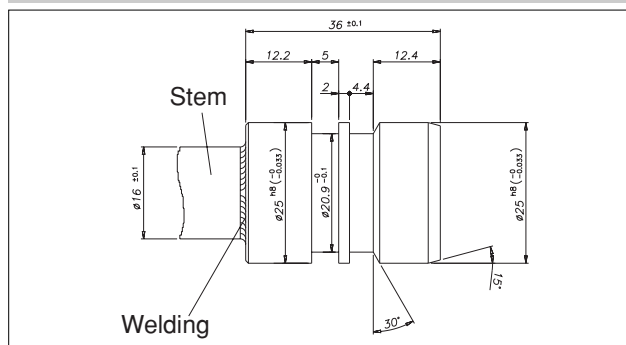
MECHANICAL / ELECTRICAL DATA

MODEL		50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
Useful electrical stroke (C.E.U.) + 1 / -0	mm	Model																			
Theoretical electrical stroke (C.E.T.) ± 1	mm	C.E.U. + 1																			
Resistance (C.E.T.)	kΩ	5						10						20							
Independent linearity (within C.E.U.)	±%	0,1		0,05																	
Dissipation at 40°C (0W at 120°C)	W	1	2	3																	
Max applicable voltage	V	40	60																		
Mechanical stroke (C.M)	mm	C.E.U. + 5																			
Case Lenght (A)	mm	C.E.U. + 94																			

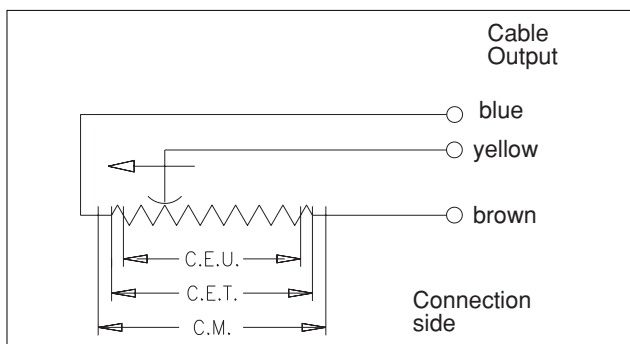
PCUR032 CURSOR



CASE DIMENSION



ELECTRICAL CONNECTIONS



ORDER CODE

Displacement transducers

PMI

12

F

X

Dimensions 1/2"

3-pole PVC cable output 3x0,25 1m

Model

Free code

If requested, it is possible to supply models with non-standard mechanical and/or electrical features

Example: **PMI-12-F-400-X 0000-X000-XX-00-XXX**
PMI 12 model transducer, useful electrical stroke (C.E.U.) 400mm.

Included in the delivery

- Displacement Transducer PMI series
- N° 1 Magnetic cursor

code: **PCUR032**

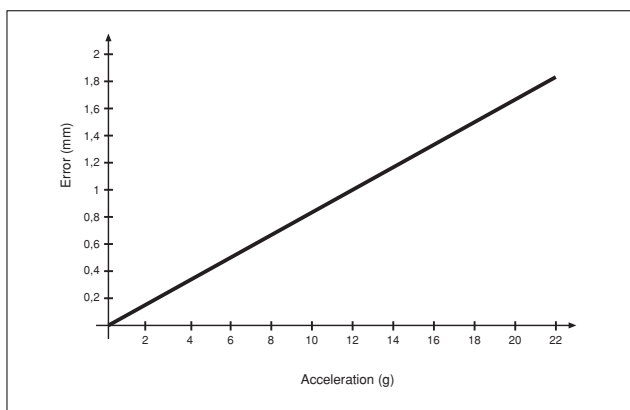
CODE EXTENSION

0 0 0 0 X 0 0 0 X X 0 0 X X X

CABLE LENGTH (1mt F standard version)

F output 00 = 1mt 02 = 2mt 03 = 3mt 04 = 4mt 05 = 5mt
10 = 10mt 15 = 15mt

TRACKING ERROR



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cod. 84971 -11/01

IC

RECTILINEAR DISPLACEMENT TRANSDUCER FOR MOUNTING INSIDE HYDRAULIC ACTUATORS



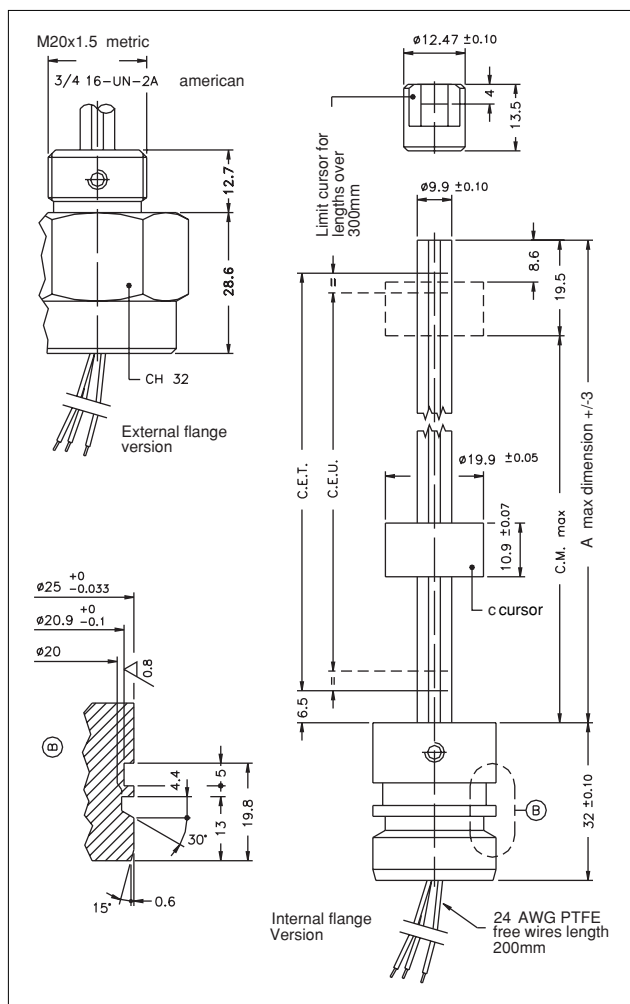
Main features

- 100 to 550 mm stroke
- Mechanical fixing by internal or external flange
- Independent linearity $\pm 0,1\%$
- Infinite resolution
- Repeatability 0,01 mm.
- No variation of electrical signal outside theoretical electrical stroke
- Displacement speed up to 1,5 m/s
- Working temperature: -30...+100°C
- Electrical connections:
IC C 6-pole connector
IC F 3 free wires (200 mm length).
- Life duration: > 25x10⁶ meters or >100x10⁶ operations, whichever is the smaller (within C.E.U.)
- Max. operating pressure 340 bar (5000 psi)

TECHNICAL DATA

Model	100/150/200/300/350/500/550
Independent linearity (within C.E.U.)	± 0,1%
Vibrations	5...2000Hz, Amax =0,75 mm amax. = 20 g
Shock	50 g, 11ms.
Tolerance on resistance	± 20%
Recommended cursor current	< 0,1µA
Maximum cursor current	10 mA
Dissipation at 40°C (0W at 120°C)	3W
Maximum applicable voltage	60 V
Temperature Coefficient of the resistance	-200 ± 200 ppm/°C
Actual Temperature Coefficient of the output voltage	< 1,5 ppm/°C
Electrical isolation	> 100MΩ at 500V=, 1bar, 2s
Dielectric strength	< 100µA at 500V~, 50Hz, 2s, 1bar
Working temperature	-30...+100°C
Storage temperature	-50...+120°C
Displacement speed	≤ 1.5 m/s
Displacement force	≤ 1 N
Stem material	Anodised aluminium
Flange material	Stainless steel AISI 303
Fixing	Internal or external flange

MECHANICAL DIMENSIONS

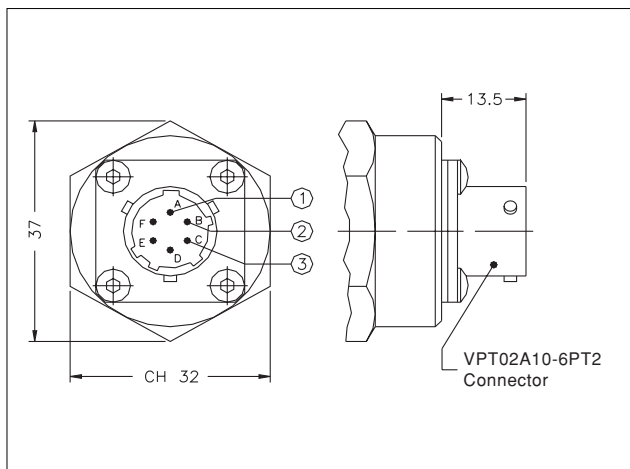


Important: all the data reported in the catalogue linearity, lifetime, temperature coefficient are valid for a sensor utilization as a ratiometric device with a max current across the cursor $I_c \leq 0.1 \mu A$.

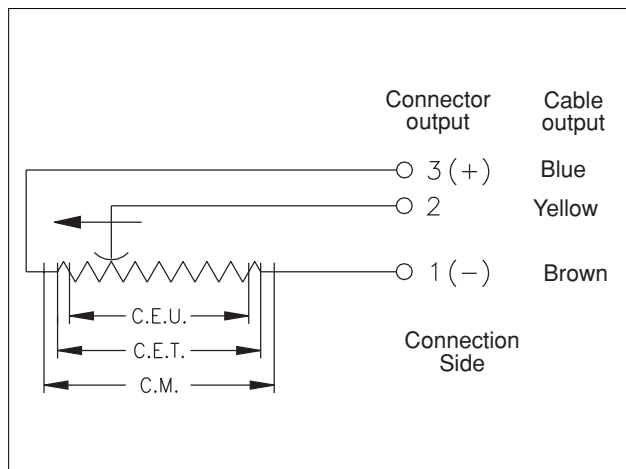
MECHANICAL / ELECTRICAL DATA

MODEL		100	150	200	300	350	500	550
Useful electrical stroke (C.E.U.) ± 1	mm	MODEL + 4						
Theoretical electrical stroke (C.E.T.) ± 1	mm	MODEL + 10						
Resistance (C.E.T.)	k Ω	10						
Mechanical stroke (C.M.) ± 1	mm	MODEL + 4						
Maximum length (A)	mm	123,5	173,5	223,5	323,5	373,5	523,5	573,5

EXT. FLANGE VERSION / CONNECTOR



ELECTRICAL CONNECTIONS



OPTIONAL ACCESSORIES

IC application manual

Code
DOC 020

Connectors
Only for external flange version

CON300
(6 pole Female connector)

ORDER CODE

Displacement transducer **IC**

3 free wires 200mm length output	F
Connector output (only for ext. flange version)	C
MODEL	
Int. flange version	I
Ext. flange version	E

Thread	
Internal flange	---
External flange	Metric M
	American I

If requested, it is possible to supply models with non-standard mechanical and/or electrical features

Example: IC - F - 300 - E - M
Displacement transducer model IC, 3 free wires 200mm. length output, external flange, metric thread and useful electrical stroke (C.E.U.) 304mm.

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cod. 84887-08/01



Main features

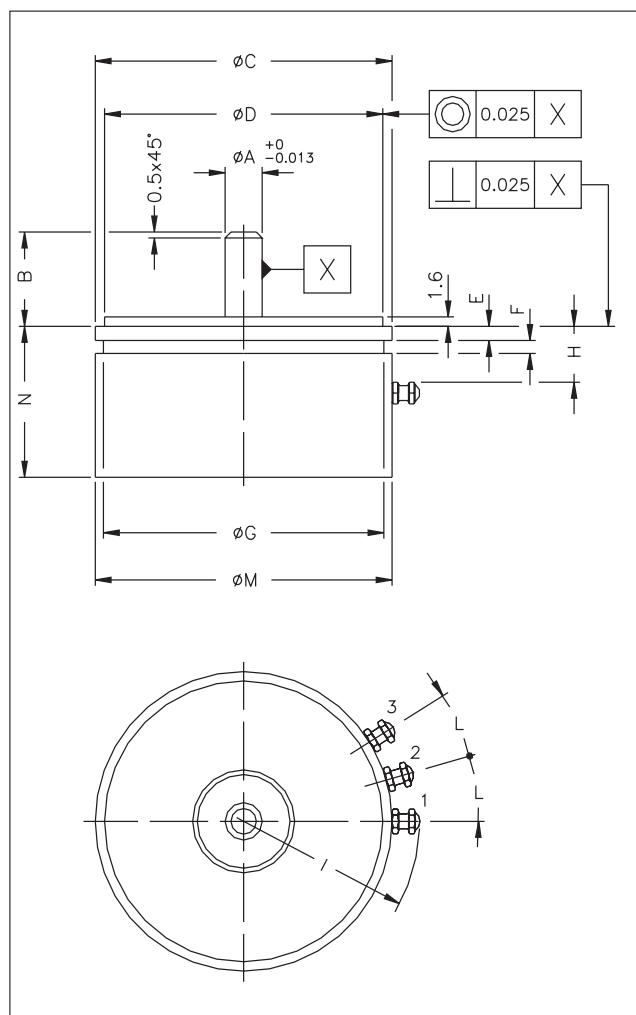
- Models 09, 11, 20
- Servo mounting
- Independent linearity up to $\pm 0,05\%$ (standard $\pm 0,5\%$)
- Repetibility 0,01% C.E.T.
- Rotation speed ≤ 600 r.p.m.
- Life duration: $>100 \times 10^6$ operations at 10 r.p.s. (within C.E.U.)
- Infinite resolution
- Electrical terminals: turrets
- Grade of protection IP40

TECHNICAL DATA

Model	09 - 11 - 20
Vibrations	5...2000Hz, $A_{max} = 0,75$ mm $a_{max.} = 20$ g
Shock	50 g, 11ms.
Hysteresis (backlash)	$\leq 15''$ of arc
Intermediate pick-offs (TAPS)	on request (max. 4)
Electrical terminals	Gold plated turrets
Torque	$\leq 0,20$ Ncm
Rotation speed	≤ 600 r.p.m.
Life duration (within C.E.U.)	$>100 \times 10^6$ operations
Tolerance on resistance total	$\pm 20\%$ other values by request
Recommended cursor current	$< 0,1 \mu A$
Maximum cursor current	10mA
Electrical isolation	$>100 M\Omega$ at 500V~, 1bar, 2s
Dielectric strength	$< 100 \mu A$ at 500V~, 50Hz, 2s, 1bar
Dissipation at 40°C (0W at 120°C)	see table
Temp. Coeff. of the resistance	-200 ± 200 ppm/°C
Actual Temperature Coefficient of the output voltage	$< 1,5$ ppm/°C
Working temperature	$-55...+100^\circ C$
Storage temperature	$-55...+125^\circ C$
Case material	Diallylphthalate
Shaft material	AISI 316
Bearings	High precision with double (ZZ) sealed screen in stainless steel
Flange	Anodised aluminium

Important: all the data reported in the catalogue linearity, lifetime, temperature coefficient are valid for a sensor utilization as a ratiometric device with a max current across the cursor $I_c \leq 0.1 \mu A$.

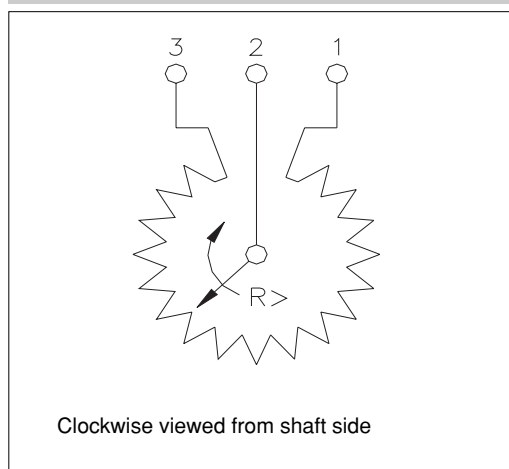
MECHANICAL DIMENSIONS



MECHANICAL / ELECTRICAL DATA

MODEL		PS09	PS11	PS20
Theoretical electrical stroke (C.E.T.)	°	340 ± 4°	345 ± 4°	350 ± 4°
Useful electrical stroke (C.E.U.)	°	C.E.T. - 2°		
Resistance ± 20% (C.E.T.)	kΩ	1 - 4.7 - 10		
Independent linearity (within C.E.U.)	±%	A = ± 1% B = ± 0,5% C = ± 0,25% D = ± 0,1% E = ± 0,05%		
Dissipation at 40°C (0W at 120°C)	W	1	1,25	3
Mechanical rotation	°	360° continuous		
Weight	g	16	20	90

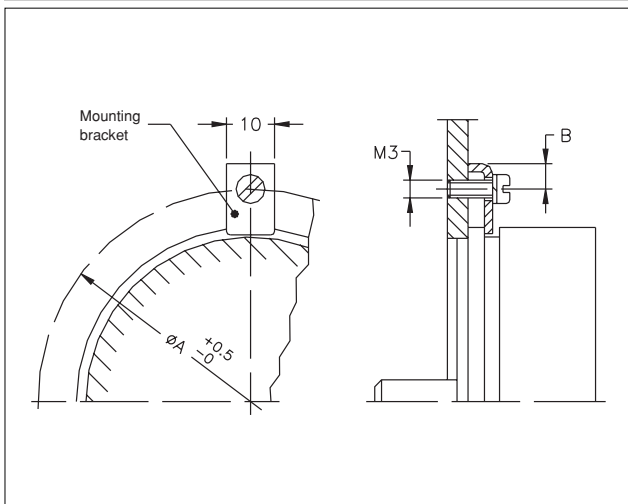
ELECTRICAL CONNECTIONS



DIMENSIONS

DIMENSIONS (mm)	DESCRIPTION	SIZE / MODEL 09 / PS09	SIZE / MODEL 11 / PS11	SIZE / MODEL 20 / PS20
ø A + 0/0.013	ø Stainless steel shaft	3.175	3.175	6.35
B max.	Shaft length	16	16	16
ø C max.	External ø of flange	22.25	27.05	50.8
ø D	ø flange	19.05	24.608	47.625
E	Tolerance on flange	+0 -0.013	+0 -0.013	+0 -0.025
F min.	Shoulder	1.6	1.6	2.4
ø G max.	Width of groove	1.5	1.5	2.2
H min.	Diameter of groove	20	25	48
I max.	Locating turrets	6	6	10
L ± 2°	Radius on turrets	16	18	30
M max.	Angle between turrets	30°	25°	15°
N max.	External ø of case	22.2	27	50.8
	Length for Nr. of elements = 1	21	21	24

MOUNTING DIAGRAM



ORDER OCODE

Rotative transducer PS

Model

Linearity (std. B)

A = ± 1%
B = ± 0,5%
C = ± 0,25%
D = ± 0,1%
E = ± 0,05%

TAPS (std. 0) **0**

Resistance value (std. 103)	1kΩ	102
	4,7kΩ	472
	10kΩ	103

If requested, it is possible to supply models with non-standard mechanical and/or electrical features

Example: PS20 - 1 - B - 0 - 103
 Rotative transducer model PS20, 1 resistive element, linearity ± 0,5%, no voltage or current intermediate pick-offs, 10kΩ resistance.

OPTIONAL ACCESSORIES

	Code
Fixing kit for PS: 3 brackets, M3x8TC screws, grower	
Rotative transducers PS09 - PS11	PKIT012
Rotative transducers PS20	PKIT013

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cod. 84893-08/01



- *Sealed industrial version*
- *Independent linearity up to $\pm 0,05\%$ (standard $\pm 0,5\%$)*
- *Working temperature: $-55...+100^{\circ}\text{C}$*
- *Repetibility 0,01% della C.E.T.*
- *Life duration: $>100 \times 10^6$ operations at 10 r.p.s.
(within C.E.U.)*
- *Infinite resolution*
- *Electrical connection: 5-pole connector DIN 43322*
- *Grade of protection IP65*

MECHANICAL DIMENSIONS

Technical drawing of a mechanical part, likely a pressure washer trigger gun, showing front and side views with dimensions.

Front View Dimensions:

- Overall width: $\varnothing 55$
- Overall height: 50
- Top section height: 14 (with tolerance ± 0.5)
- Section below top: 40
- Section below 40: 3
- Bottom section height: 8
- Bottom mounting hole: $M16 \times 0.75$

Side View Dimensions:

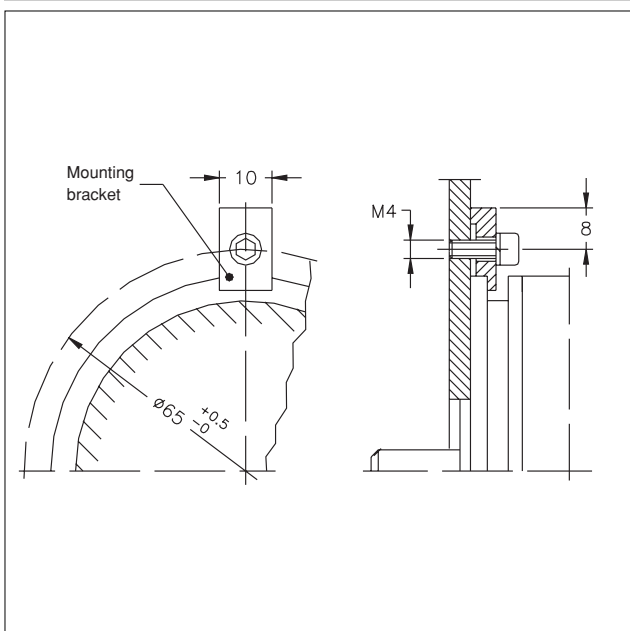
- Overall width: $\varnothing 48$
- Inner hole diameter: $\varnothing 20$ (tolerance $h5$)
- Inner hole depth: 6 (tolerance $g5$)
- Threaded section: $0.5 \times 45^\circ$
- Top flange thickness: 1.5 (tolerance $+0.1 / -0$)
- Bottom flange thickness: 2.4

Important: all the data reported in the catalogue linearity, lifetime, temperature coefficient are valid for a sensor utilization as a ratiometric device with a max current across the cursor $I_c \leq 0.1 \mu A$.

MECHANICAL / ELECTRICAL DATA

MODEL		PR65
Theoretical electrical stroke (C.E.T.)	°	345 ± 4°
Useful electrical stroke (C.E.U.)	°	C.E.T. - 2°
Resistance (C.E.T.)	kΩ	1 - 4.7 - 10
Independent linearity (within C.E.U.)	±%	A = ± 1% B = ± 0,5% C = ± 0,25% D = ± 0,1% E = ± 0,05%
Dissipation at 40°C (0W at 120°C)	W	1.25
Mechanical rotation (C.M.)	°	360° continuous
Weight	g	132

MOUNTING DIAGRAM

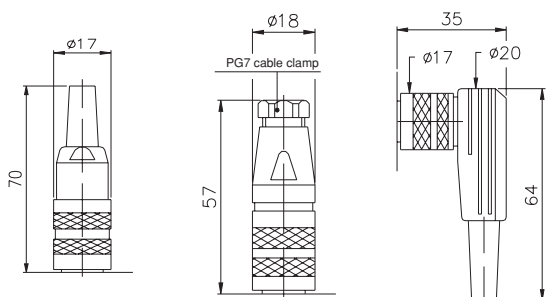


OPTIONAL ACCESSORIES

Fixing kit for PR65:
3 brackets, M4x10TCEI screws, grower

Code

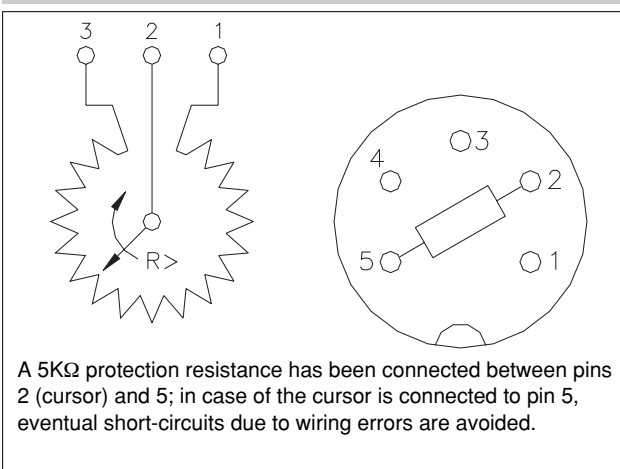
PKIT008



CON011 - IP40 Prot. (5 pole Female conn.)
CON012 - IP67 Prot. (5 pole Female conn.)
CON013 - IP40 Prot. (5 pole Female conn.)

Extraction length of the connector 10mm.

ELECTRICAL CONNECTIONS



ORDER CODE

Rotative transducer **PR65**

Linearity (std. B)	A = ± 1%
	B = ± 0,5%
	C = ± 0,25%
	D = ± 0,1%
	E = ± 0,05%

TAPS (std. 0)	0
---------------	----------

Resistance value (std.103)	1kΩ	102
	4,7kΩ	472
	10kΩ	103

If requested, it is possible to supply models with non-standard mechanical and/or electrical features

Example: **PR65 - B - 0 - 103**

Rotative transducer model PR65, linearity ±0,5%, no voltage or current intermediate pick-offs, 10kΩ resistance.

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cod. 84899-08/01



Main features

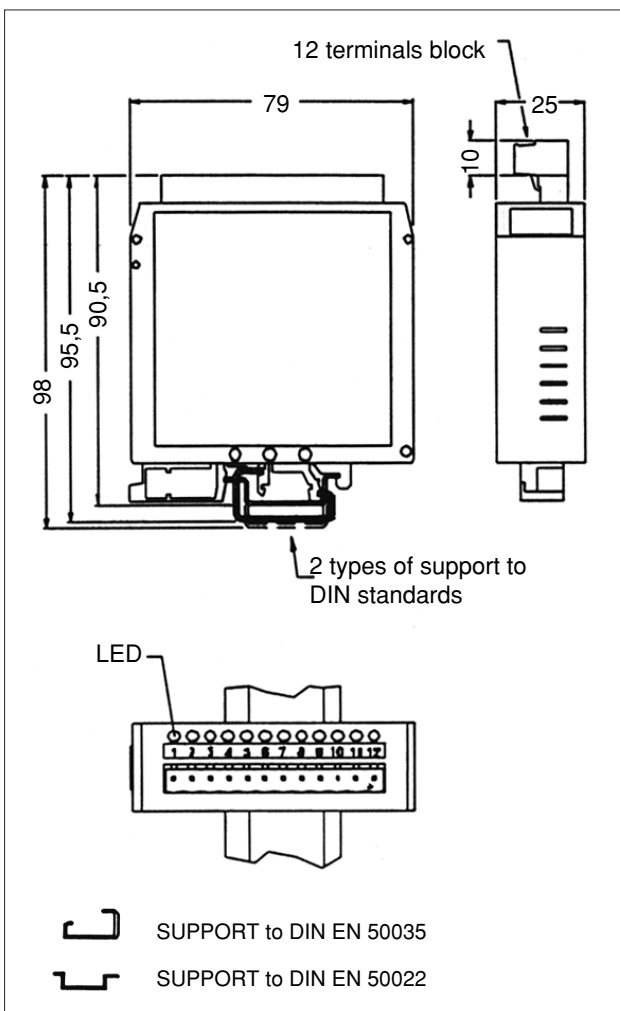
- High impedance input >100 Mohm
- Voltage output 0...10V
- Linearity error < 0,02% full scale output
- Can be connected simultaneously to two transducers
- Low thermal drift 0,01% full scale / °C
- Suitable for DIN rail mounting EN50035 and EN50022

The PCIR signal conditioners have been designed to enable the user to adapt the output impedance of linear or rotative displacement transducers in conductive plastic for acquisition systems or PLC, in a way that does not alter the linearity of the transducer itself.

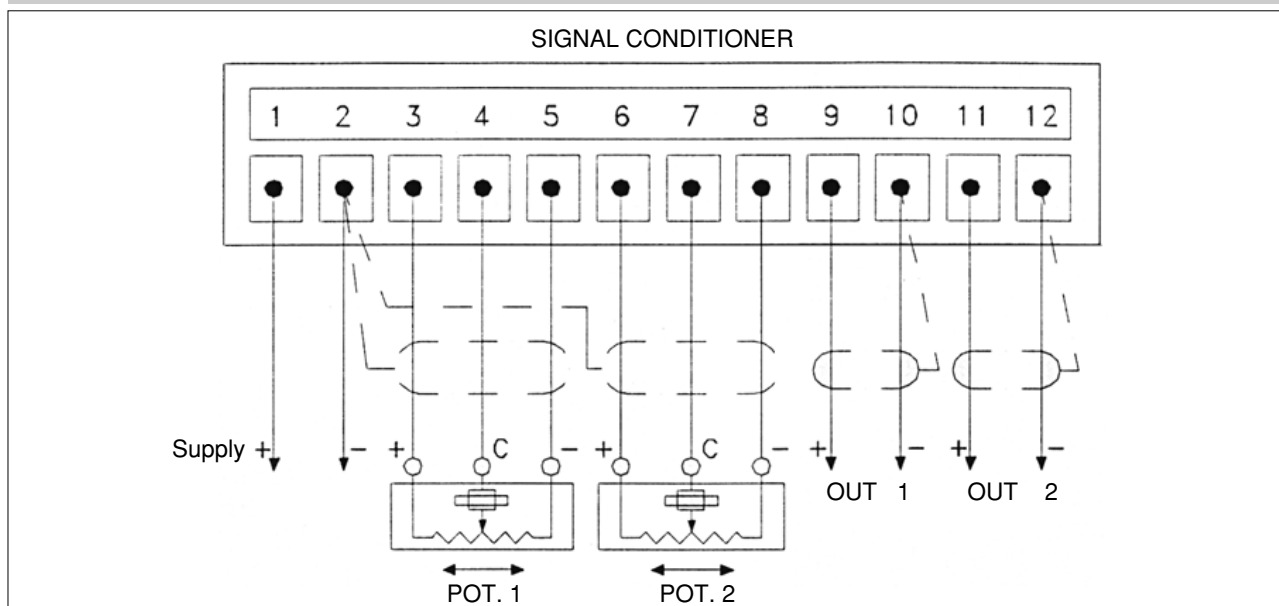
TECHNICAL DATA

Linearity error	< 0.02%FSO
Transducer resistance	1...20kΩ
Input impedance of cond.	> 100 MΩ
Output load resistance	> 10kΩ
Supply voltage	15...30Vdc
Current drain	< 70mA
Supply voltage to transducer	10Vdc
Output signal at zero	0mA
Zero signal accuracy	± 0,1%FSO
Full scale output	10Vdc
Full scale output accuracy	± 0,1%FSO
Inverse polarity protection	Yes
Output shortcircuit protection	Yes
Response time (10...90%FSO)	< 5ms
Output noise (RMS 10...400Hz)	-70 db FSO
Temperature range: Working StoStorage	-10...+70°C -50...+100°C
Typical thermal drift of zero	± 0.01%FSO/°C
Typical thermal drift of span	± 0.01%FSO/°C
Case material	Polyamide
Protection degree	IP30 - EN60529

MECHANICAL DIMENSIONS



ELECTRICAL CONNECTIONS



OPTION ACCESSORIES

Cables and assembled cables **on request**

ORDER CODE

MODEL	
Output signal 0...10Vdc	A

PCIR

Example.:PCIR

Signal conditioner for linear or rotary displacement transducers with output signal at full scale of 10Vdc.

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cod. 84935-08/01

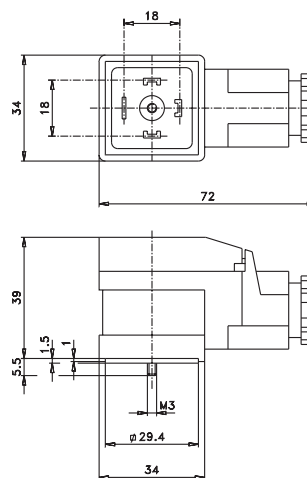


- Interface module integrated in the connector
- Standard output 0...10Vdc (PCIR 101)
- Standard output 4...20mA(PCIR 102)
- High linearity
- Low zero and span thermal drift
- Adjustable Zero and Span

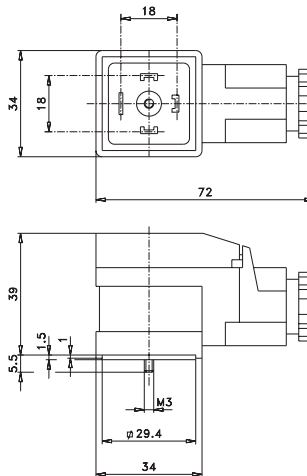
TECHNICAL DATA

MECHANICAL DIMENSIONS

PCIR101



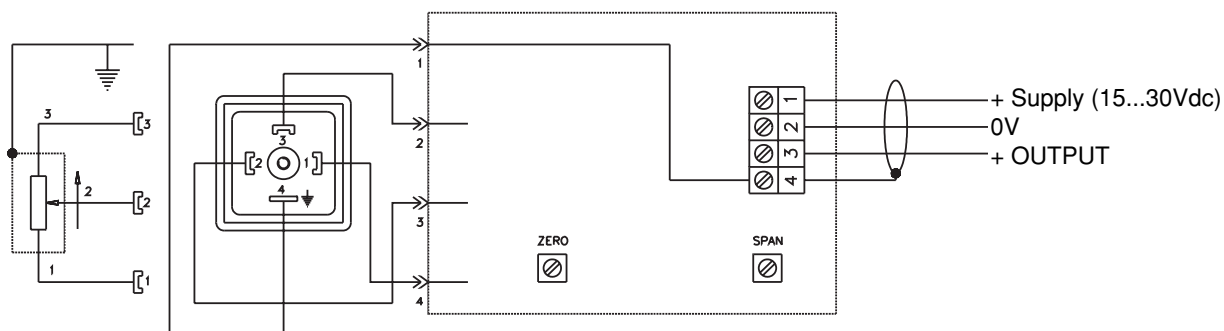
PCIR102



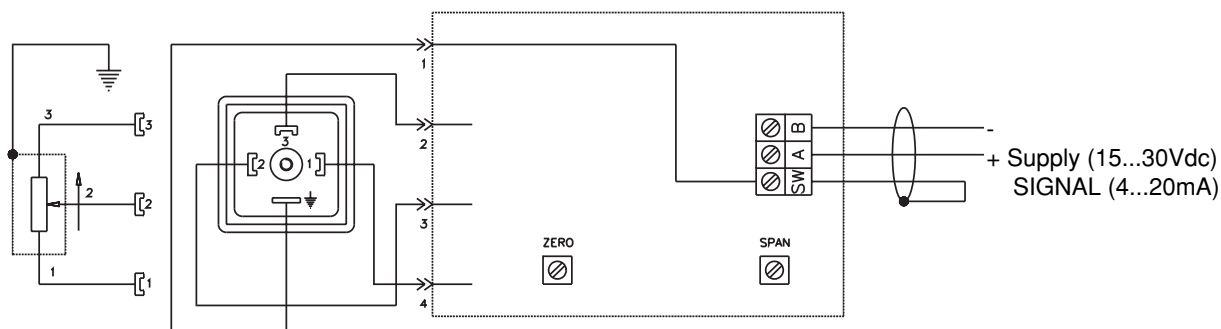
FSO: Full Scale Output (output signal at nominal pressure)

ELECTRICAL CONNECTIONS

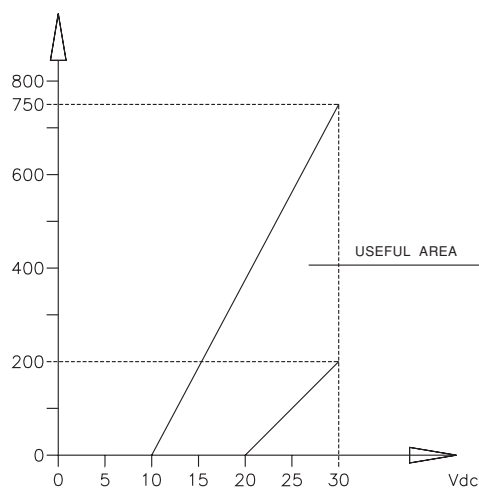
PCIR101



PCIR102



LOAD DIAGRAM



The diagram at side shows the optimum ratio between the load and supply voltage for the 4...20mA conditioner. For a correct function it is necessary to use a combination of load resistance and supply voltage that falls within the shaded area.

ORDER CODE

PCIR 10

OUTPUT	
0...10Vdc	1
4...20mA	2

Non standard mechanical and / or electrical features are available on request.

Ex.: **PCIR 101**

Signal conditioner with 10Vdc output.

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code 84947 - 08/01



Main features

- Simple networking solution
- Low cost digital communication
- Reduces the cost and time to wire and install industrial automation devices
- Interchangeability
- Transmission speed 500k baud (max. 1000M baud)
- Typical application: slave
- Easy configuration node

The "CAN Field Bus Adapter" (CFBA) development is for an easy configuration node. By software, or only with some electrical connections on the board, is possible establish: **Baud Rate, Node-Identifier, the direction of the signal in case of potentiometric sensor.**

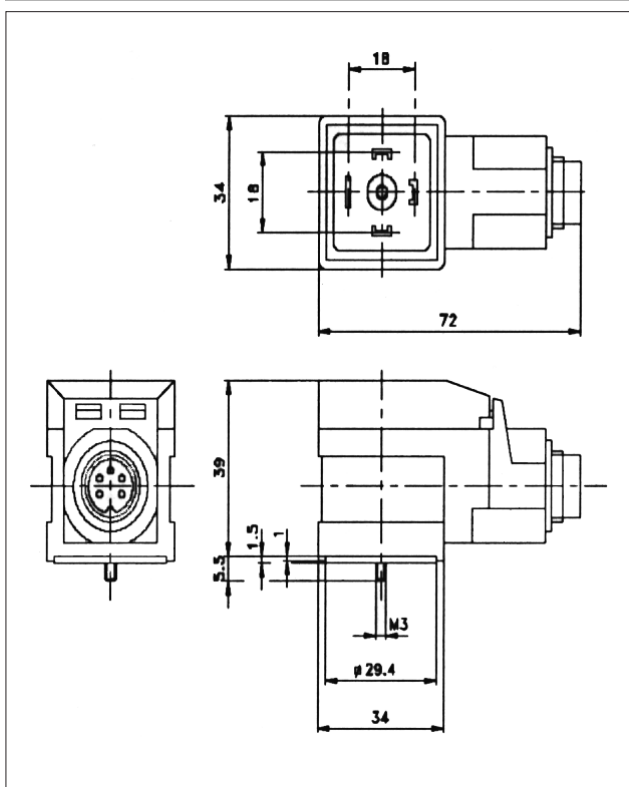
The particular structure of CFBA, the small encumbrance and the connections, facilitates the converting of systems to this networking solution.

The type P of CFBA is suited of potentiometric displacement transducers and the supply voltage $V_s(5V)$ of the transducer is ratiometric with V_{ref} of ADC. In the type V, V_s on analog port is the same of the V_{cc} on signal port. In this case the standard range for analog input V_{in} is 5V (2,5 or 10V if jumper WP1 on the board is set). Other values on request. The CFBA includes all hardware modules necessary to implement the CAN Transfer Layer, which represents the kernel of the CAN Bus protocol. Up to message level, the CFBA is totally compatible with the basic CAN and the full CAN implementation. Functional differences are related to the object layer only. Whereas a full CAN controller provides dedicated hardware for handling a set of messages, the CFBA is restricted to receiving and/or transmitting messages on a messages by message basis. It will never initiate an Overload Frame.

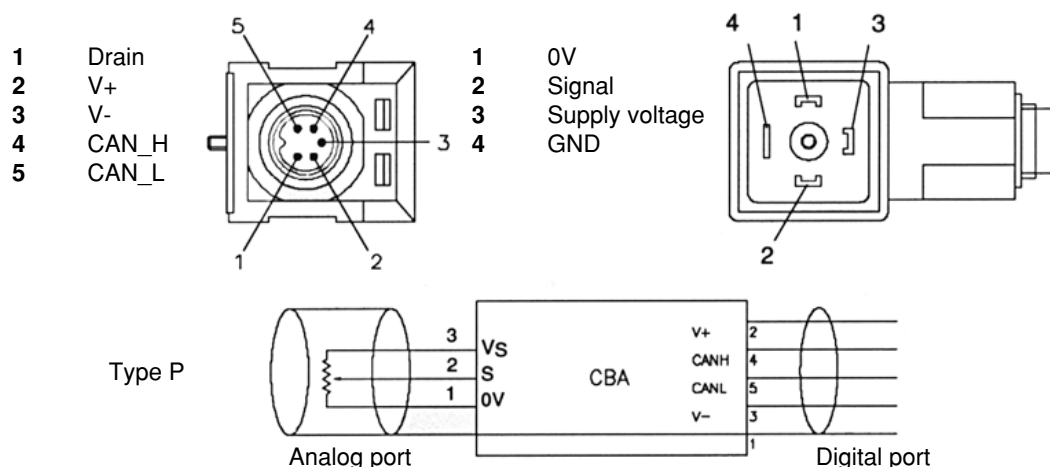
TECHNICAL DATA

General Characteristics						
Symb.	Parameter	Condit.	Min	Typ.	Max	Unit
V_{cc}	Supply voltage		7,5		35	Vdc
I_{cc}	Supply current		20			mA
	Resolution			12		bits
	No missing codes		12			bits
	Integral linearity			± 1		LSB
	Differential linearity			$\pm 0,5$		LSB
	Offset error			0,75		LSB
	Gain error			± 2		LSB
	Conversion time		180			μ sec
T_{AMB}	Operating amb. temp.		-20		+80	$^{\circ}C$
T_{AMB}	Storage amb. temp.		-30		+85	$^{\circ}C$
Analog port						
Symb.	Parameter	Condit.	Min	Typ.	Max	Unit
V_s	Supply output voltage	type P	4,8	5	5,2	Vdc
		type V		V_{cc}		Vdc
R_{LOAD}	Load resistance		500			Ω
V_{IN}	Analog input	no shunt			5	Vdc
		shunt			50	Vdc
R_{IN}	Input resistance	no shunt		10		M Ω
		shunt	100			k Ω
Digital port						
Symb.	Parameter	Condit.	Min	Typ.	Max	Unit
1/tbit	Transmission speed	NRZ			1	Mbaud
V_{CAN}	Input/Output voltage CANH, CANL		-8		+18	Vdc
ΔV	Differential bus voltage transmitter		1,5		3,0	Vdc
I_{SCH}	Short-circuit CANH current	$V_H = 5$			105	mA
I_{SCL}	Short-circuit CANL current	$V_L = +18$			160	mA
R_i	CANH/CANL input res.		5		25	k Ω
R_{diff}	Differential input res.		20		100	k Ω
C_i	CANH, CANL input capacitance				20	pF
C_{diff}	Differential input capacitance				10	pF

MECHANICAL DIMENSIONS



ELECTRICAL CONNECTIONS



PHYSICAL / MEDIA CHARACTERISTICS

The list below presents a summary of the Physical/Media specific characteristics (for fully details of the Device Net please refer to the published specifications).

- Support for up to 64 nodes
- Node removal without severing the network
- Simultaneous support for both network-powered (sensors) and self-powered (actuators) devices
- Protection from wiring errors
- Selectable data rates of 125, 250 e 500kbaud

Baud rate	Trunk Distance	Drop Length	
		Max	Cumulative
125kBits/s	500m (1640 ft)	6m (20ft)	156m (512ft)
250kBits/s	250m (820 ft)	6m (20ft)	78m (256ft)
500kBits/s	100m (410 ft)	6m (20ft)	39m (128ft)

- High current capability (up to 16A per supply)
 - Standard connections
 - Built-in overload protection
 - Power available along the bus: both signal and power lines contained in the cable.
- We recommended Belden Device Bus for Device Net 1485-P1-C or equivalent.

OPTIONAL ACCESSORIES

ORDER CODE

CFBA

MODEL	
Type	P
Type	V

Es.: **CFBA - P**

Can Field Bus Adapter for potentiometric transducer

GEFRAN spa reserves the right to make any kind of design or functional modification at any moment without prior notice



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code 84966 - 08/01



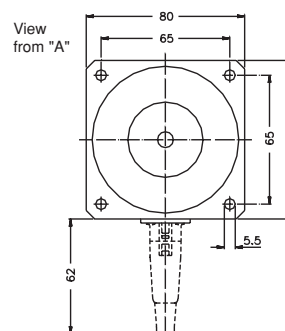
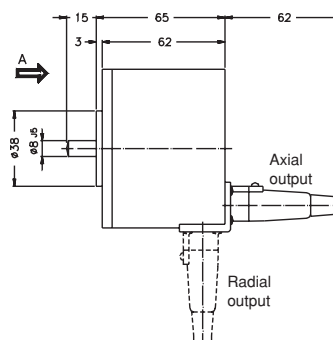
Main features

- Monodirectional encoder with position hysteresis; outputs x1, x2, x4 (EG01)
- Monodirectional or bidirectional, with or without separate zero reference output, encoder (EG02)
- Tachometer with analogue output proportional to the speed and digital output (EG03)
- The power supply requirements and output signal levels are compatible with all the GEFran instruments.

MECHANICAL DIMENSIONS AND DATA

TECHNICAL DATA

EG01	Monodirectional with hysteresis of the position signal, outputs x1, x2, x4
EG02	Monodirectional, bidirectional, or bidirectional with zero position reference signal (EG02)
EG03	Monodirectional with an analogue output proportional to angular speed (1V/100 r.p.m. - 1V/1000 r.p.m.) depending on scale range, and a digital output which retransmits the fundamental frequency of the encoder (EG03)
Supply	5V , 8...24V (EG01-EG02) - 11...25V (EG03)
Max. consumption	30mA (free outputs)
Digital output	Supply 8...24V VH = Vcc-2V; IOH = 2mA; VL 0.8V; I max = 30mA Supply 5V VH = 2.4V; IOH = 0,7mA; VL 0.4V; FAN OUT = 8TTL
Frequency	Fmax = 50kHz. For the output with hysteresis, the x4 signal is a train of rectangular pulses with a width of 60 µsec.
Analogue output (EG03)	1V/100 r.p.m. for range: 1 to 200 r.p.m. 1V/1000 r.p.m. for ranges: 2 to 2000 r.p.m. 5 to 5000 r.p.m.
Linearity of analogue output	0,2% F.S.
Time constant	(Time to reach 63% f.s.) 350 msec.
Digital output (EG03)	Open collector. V max. 30V, I max. 30mA 240 pulses/turn for ranges: 1 to 2000 r.p.m., 2 to 2000 r.p.m. 100 pulses/turn for range 5 to 5000 r.p.m.
Light source	Infrared LED - estimated life of 10 ⁵ hours
Connections	6 pole connector with axial or radial output



Torque	0,5 Ncm
Maximum speed	5000 r.p.m.
Moment of inertia	50gr. cm ²
Angular acceleration	2000 rad/sec ²
Axial load	30N
Radial load	34N
Working temperature	0-50°C
Relative humidity	95% non condensing
Case	Anodised aluminium flange. Cover in self-extinguishing plastic
Grade of protection	IP65
Mechanical life	10 ⁹ turns
Weight	300 g

GENERAL DATA

The output signals from channel A and B are rectangular waveforms with 50% duty cycle.

The two channels are 1/4 period out of phase or 90° electrically. The two signals enable detection of the direction of rotation, by observing the time sequence of the output pulses. In practical industrial applications, the presence of vibration can create problems with monodirectional encoders.

The method usually employed to avoid uncertainty is to design a hysteresis on the switch point level with internal logic.

This type of hysteresis could be called "analogue" since it operates on the amplitude of the output signal, and it is present on any type of optical encoder.

The EG01 not only employs "analogue" hysteresis, but uses another original type of hysteresis.

It uses the second channel to obtain the largest possible hysteresis with a logic discrimination, which is 90° electrically.

A larger width would mean loss of information, since it would be larger than the resolution of the encoder and would thus mask an output pulse.

If N is the number of pulses per turn, then the 360° mechanical-ly is equivalent to 360 x N degrees electrically.

Thus for an encoder with an output of 250 pulses per turn, 90° electrically is equivalent to 90/250=0.36 degrees mechanically.

This means that no new output pulse can occur until the encoder shaft is rotated more than 0.36°.

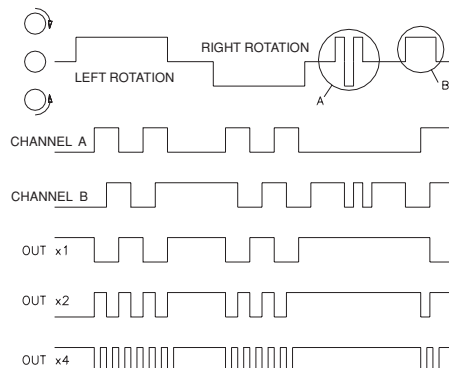
The following diagram illustrates the behaviour in the case of vibration that is less than or greater than 90° electrically (cases A and B respectively).

The x2 and x4 outputs of the encoder allow the resolution of the system to be correspondingly increased.

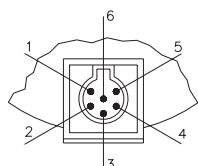
Both outputs have the property of hysteresis.

The x2 output is a logic combination of channels A and B, while the x4 output is a 60 microsecond pulse triggered by each leading and trailing edge of the pulse train obtained in the x2 output.

In the latest case, to avoid overlapping of the pulses, it is not possible to exceed a frequency of 5 kHz (1.2 kHz at the input).



ELECTRICAL CONNECTIONS



EG 01

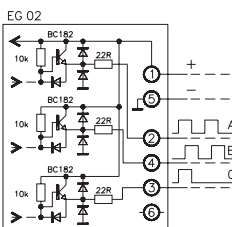
- 1+/- 5- Supply
- 2 x2 output
- 3 Not connected
- 4 x4 output (max. freq. 5 kHz)
- 5 x1 output
- 6 x1 output

EG 02

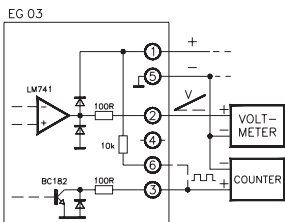
- 1+/- 5- Supply
- 2 Channel A
- 3 Zero reference signal
- 4 Channel B
- 5 Not connected
- * The channel A is present for the monodirectional version

EG 03

- 1+/- 5- Supply
- 2 Analog output
- 3 1V/1000 turns for scales 2-5
- 4 1V/100 turns for scale 1
- 5 Open collector output of encoder frequency
- 6 Not connected
- 7 Pull-up resistance for open collector (10kOhm connected internally to + V supply)



EG 02



EG 03

OPTIONAL ACCESSORIES

	Code
Mating connector	CON 801
Flexible joint	GIU 000

ORDER CODE

EG	
MODEL	
Monodirectional with position hysteresis	EG01
Mono/Bidirectional zero reference output	EG02
Tachometer	EG03
SCALE (EG03 only)	
1 to 200 r.p.m.	1
2 to 2000 r.p.m.	2
5 to 5000 r.p.m.	5
SUPPLY	
5Vcc (EG01/EG02)	A
8-24Vcc (EG01/EG02)	B
11-25Vcc (EG03)	---
OUTPUT (EG02 only)	
Monodirectional	M
Bidirectional	B
NR of pulses/rev (EG01/EG02 only)	
60 pulses/rev	60
100 pulses/rev	100
200 pulses/rev	200
240 pulses/rev	240
250 pulses/rev	250
CONNECTOR	
With radial outlet	R
With axial outlet	A
ZERO REF. SIGNAL (EG02 only)	
With zero indication	Z
Without zero indication	---

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